

Introduction to LONI QB-4 Cluster

Le Yan
Assistant Director
LONI HPC



Objectives

- Understand how QB-4's architecture and user environment are different from those of QB-3
- Understand how various factors affect application performance on QB-4



Outline

- QB-4 hardware architecture
- QB-4 user environment
- Application performance benchmarks and tuning on QB-4



QB-4 architecture and software environment



QB-4 Specs

547 Compute Nodes (35,008 CPU cores, 144 GPUs, 161 TB RAM)

480 regular nodes

2 Intel 32-core CPUs
256 GB RAM



52 2-GPU nodes

2 Intel 32-core CPUs
512 GB RAM
2 NVIDIA A100 GPUs



10 4-GPU nodes

2 Intel 32-core CPUs
512 GB RAM
4 NVIDIA A100 GPUs



5 big memory nodes

2 Intel 32-core CPUs
2 TB RAM



Infiniband NDR200 200Gb/s Fabric

6.5 PetaBytes Lustre Storage



QB-4 vs QB-3 vs QB-2



QB-2*

2014

1.5

10,192

38

89



QB-3

2020

0.9

9,696

41

85



QB-4

2024

4.3

35,008

161

307

In production since	Theoretical peak performance (PFLOPS)	CPU cores	Total RAM (TB)	SUs per year (million)
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* This is the original QB-2 before some nodes were decommissioned.



QB-4 Node Specification

CPU	Intel Ice Lake (Xeon Platinum 8358) (2 sockets *32 cores/socket)
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CPU frequency	2.6 G Hz
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Floating operation per clock cycle (double precision)	32
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Memory	256GB/512GB/2TB DDR4
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GPU	NVIDIA A100 80GB PCIe
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Interconnect	Mellanox 200 Gbps Infiniband
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QB-4 vs QB-3 (Node over Node)

	QB-4	QB-3
CPU frequency	2.6×10^9	2.4×10^9
CPU cores	64	48
Operation per cycle	32	32
Memory bandwidth	~400 GB/s	~280 GB/s
Interconnect	200 Gbps	100 Gbps

Node peak performance

QB-4: $64 \text{ cores/node} * 2.6 \times 10^9 \text{ cycles/second} * 32 \text{ flop/cycle} = 5.32 \times 10^{12} \text{ flops}$

QB-3: $48 \text{ cores/node} * 2.4 \times 10^9 \text{ cycles/second} * 32 \text{ flop/cycle} = 3.69 \times 10^{12} \text{ flops}$

Theoretical speedup = 1.4



Software Environment (1)

Operating System	RHEL 8.8
Workload Manager	Slurm
Software Environment Manager	Environment Module
Container Engine	Singularity
Default Toolchain (Compiler + MPI)	Intel 2021.5.0 Intel MPI 2021.5.1

The QB-4 Open OnDemand portal will be available soon!



Software Environment (2)

```
$ module av
```

```
-- /project/containers/modulekeys -
```

```
agat/1.4.0      blast/2.14.1   busco/5.7.1  
jellyfish/2.3.0  octopus/14.0
```

```
-- /usr/local/packages/Modules/default/modu  
icelake --
```

```
amber/22/intel-2021.5.1-intel-mpi-2021.5.1  
gsl/2.7.1/intel-2021.5.0  
parallel-netcdf/1.12.3/intel-2021.5.0-intel-mpi-2021.5.1  
hdf5/1.12.2/intel-2021.5.0-intel-mpi-2021.5.1  
parallel/20220522/intel-2021.5.0  
boost/1.83.0/intel-2021.5.0
```

Use the “module av” command to list all installed packages.

Software packages are installed either by compilation or as container images. The difference should be minimal from the users’ point of view.

If a package is missing, please submit a ticket to sys-help@loni.org,



Workload Management (1)

- List of job partitions/queues

single	Jobs that will only execute on a single node. Default queue.
checkpt	Jobs that use multiple nodes and are preemptable.
workq	Jobs that use multiple nodes.
bigmem	Jobs that use the big memory nodes (2TB per node).
gpu2	Jobs that use GPUs on the 2-GPU nodes.
gpu4	Jobs that use GPUs on the 4-GPU nodes.



Workload Management (2)

- GPU jobs can request less than a whole node

On **QB-3** a GPU job must request at least a GPU node, i.e. two GPU devices:

```
$ srun -p gpu -N1 -A loni_my_allocation my_gpu_executable
```

On **QB-4** a GPU job can request one GPU device on a GPU node with 2 or 4 GPUs:

```
$ srun -p gpu2 -N1 --gres=gpu:1 -A loni_my_allocation my_gpu_executable
```

On **QB-4** a GPU job can request three GPU devices on a GPU node with 4 GPUs:

```
$ srun -p gpu4 -N1 --gres=gpu:3 -A loni_my_allocation my_gpu_executable
```




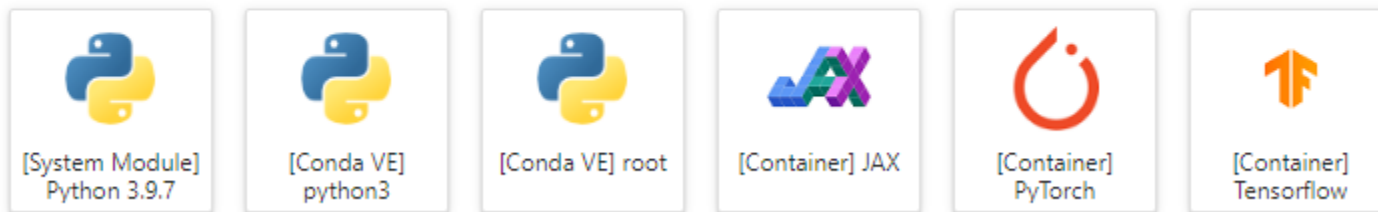
AI/DL Frameworks

- All AI/DL frameworks are installed via container images and/or Conda VE's
 - Command line

```
jax/0.4.26      pytorch/2.2.2      tensorflow/2.16.1
```

- Open OnDemand portal (coming soon)

 Notebook



Policy Update (1)

- Max SUs for a single allocation: 6M -> **8M**
- Total max active SUs per PI: 12M -> **16M**
- Startup allocation threshold: 50K -> **150K**
- **Instructional allocations**
 - A new type of allocations for courses and/or training activities
 - Limit: 150K SUs
 - Can be submitted and reviewed at any time
 - PI still needs to provide a justification in the form of a proposal



Policy Update (2)

- Higher charge rate for the A100 GPUs on QB-4
 - Each A100 GPU is treated as a regular compute node (64 CPU cores)

A job runs 2 hours on a **QB-3** GPU node (2 V100 GPU devices):

Charge = 2 hours * 48 CPU cores = 96 SUs

A job runs 2 hours on a **QB-4** 2-GPU node using both A100 GPUs:

Charge = 2 hours * 2 GPU devices * 64 CPU cores/GPU device = 256 SUs

A job runs 2 hours on a **QB-4** 4-GPU node using all four A100 GPUs:

Charge = 2 hours * 4 GPU devices * 64 CPU cores/GPU device = 512 SUs

Application Performance Benchmarks and Tuning



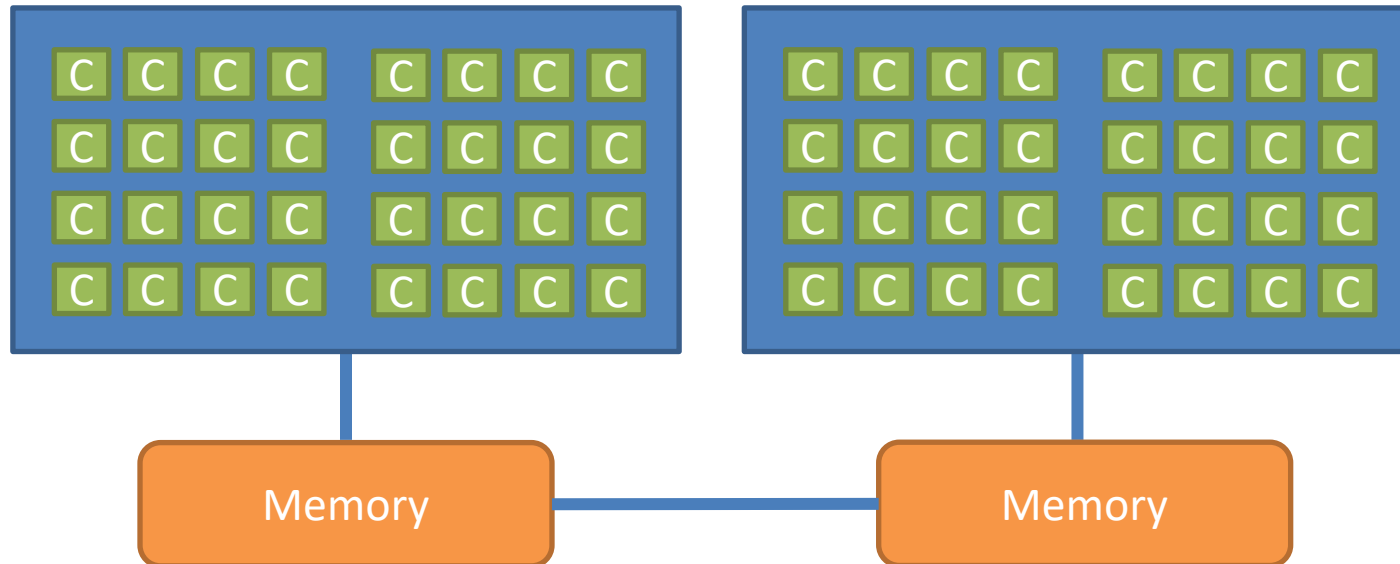
Disclaimer

- Target audience: users who run (and sometimes compile) applications developed by others
 - Not an in-depth guide for programmers and developers



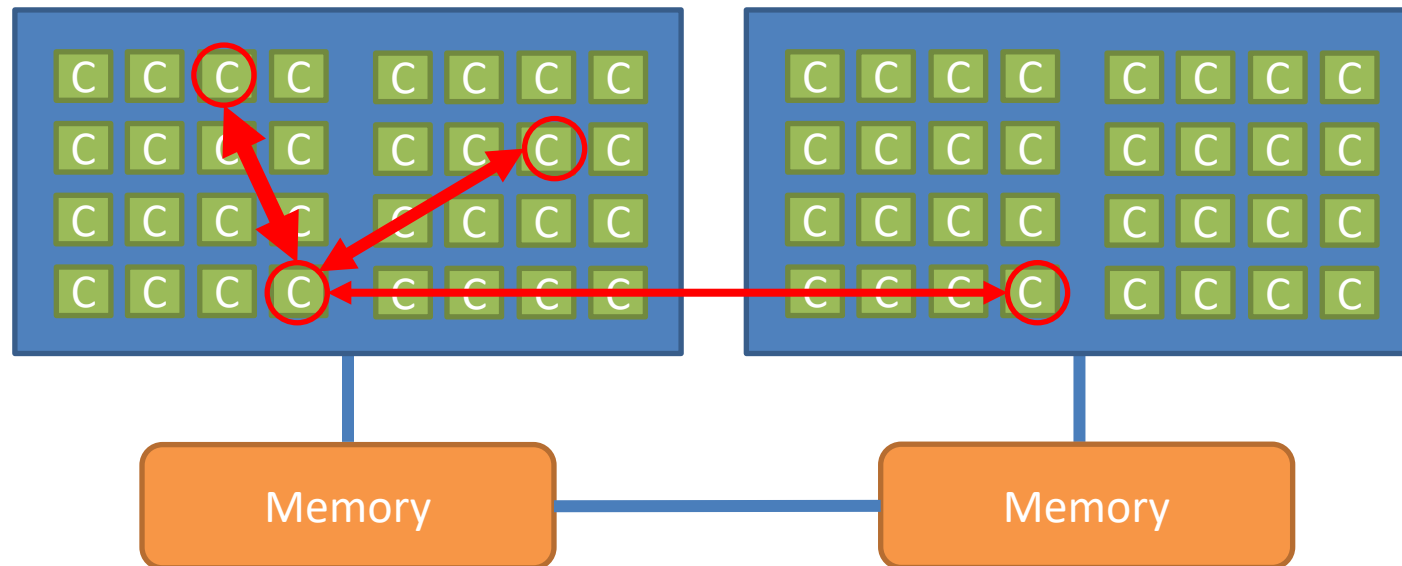
QB-4 Architecture – Node Level

Node level view



QB-4 Architecture – Node Level

Node level view

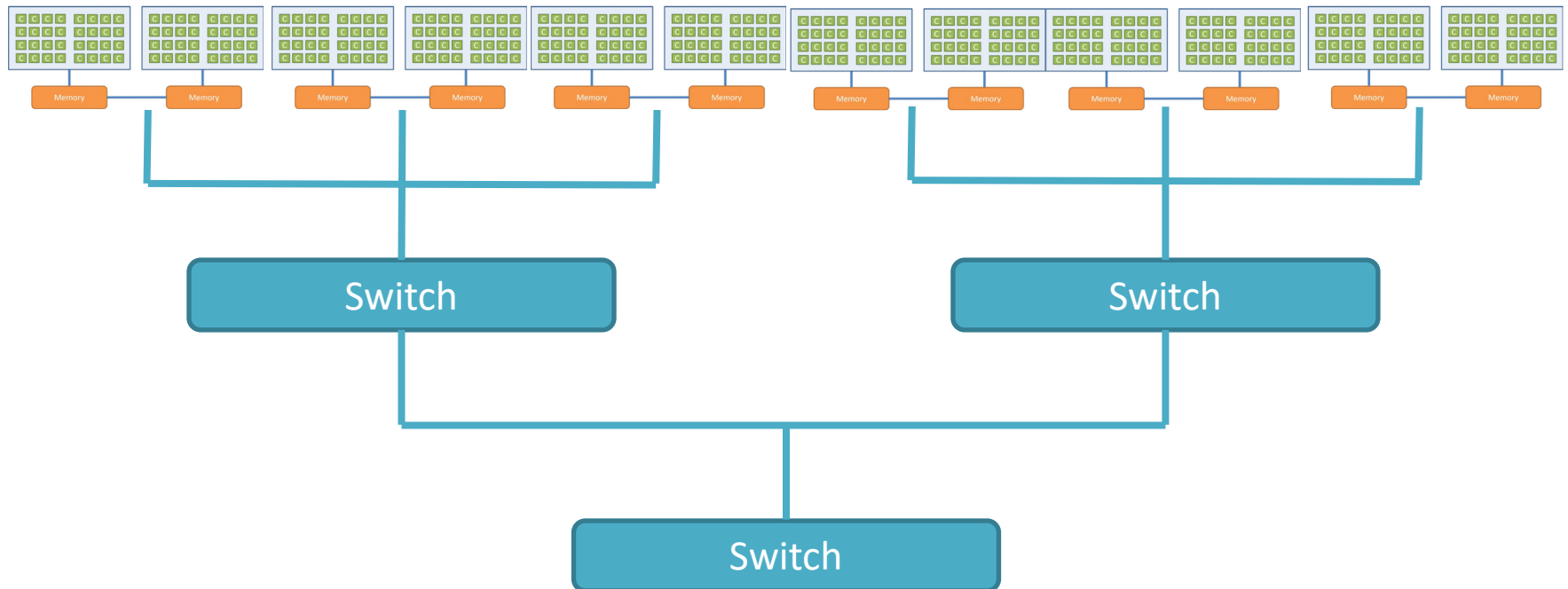


- The 64 cores on a QB-4 node are grouped into 4 sets.
- The data exchange cost is not homogeneous.
- Depending on the data exchange pattern, how the threads are arranged could affect performance significantly.

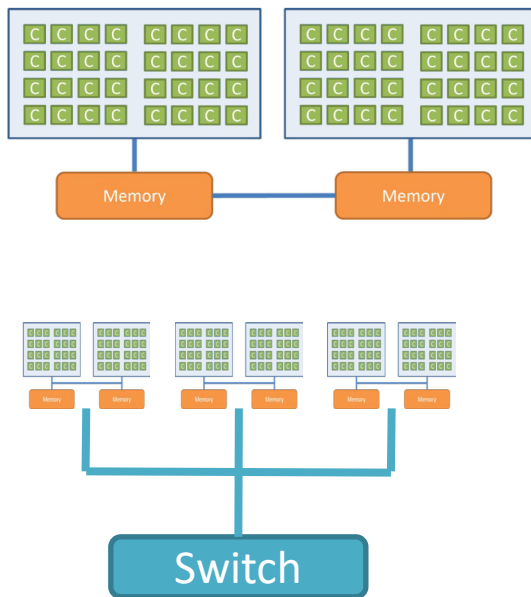


QB-4 Architecture – Cluster Level

Cluster level view



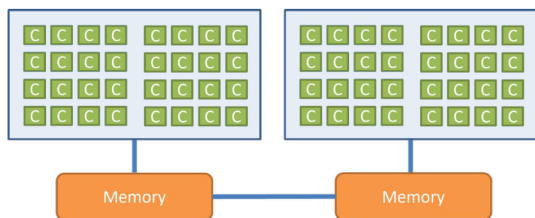
Why This Matters



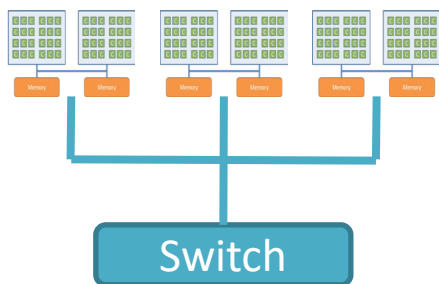
- Keys for good performance
 - Distribute the workload (well) among the CPU cores
 - Keep the CPU cores busy by keeping them well fed (with data)
- Data supply efficiency depends on their relative positions within the hierarchy
- Applications are
 - **CPU-bound** if CPU cores are well fed
 - **Memory-bound** (or I/O bound) if CPU cores are hungry most of the time



Parallel Paradigms



Intranode
(data exchange
through **memory**)



Internode (data
exchange through
network)

Pro

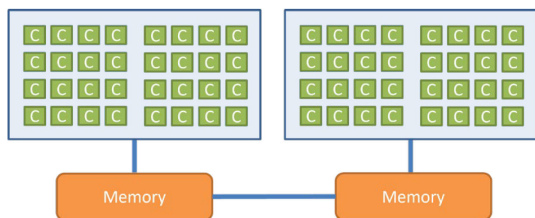
- Low latency, high bandwidth
- Implicit communication
- Fine granularity
- (Relatively) Easy to balance the load

Con

- Shared memory system only (Limited to one node)
- High latency, low bandwidth
- Explicit communication
- Hard to balance the load



Parallel Paradigms



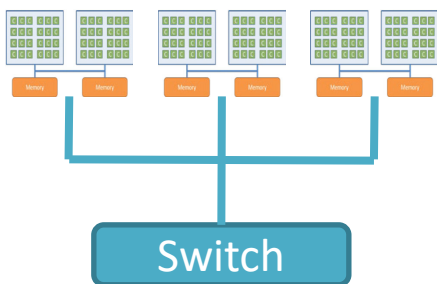
Intranode
(data exchange through **memory**)

OpenMP (Multi-threaded)

- Low latency, high bandwidth
- Implicit
- (Relatively) Easy to balance the load

Con

- Shared memory system only
- Limited to one node



Internode (data exchange through **network**)

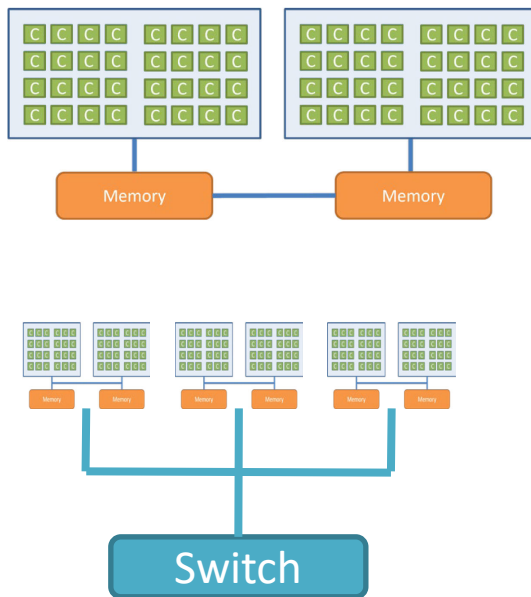
MPI (Multi-process)

- Scalability beyond 1

- High latency, low bandwidth
- Explicit communication
- Hard to balance the load



What About MPI+OpenMP Hybrid?



- Getting the benefits from both worlds?
- In theory, yes
- But adding OpenMP to (well-written) MPI programs might hurt the performance
- Hybrid helps to
 - Reduce memory footprint
 - Extend scalability

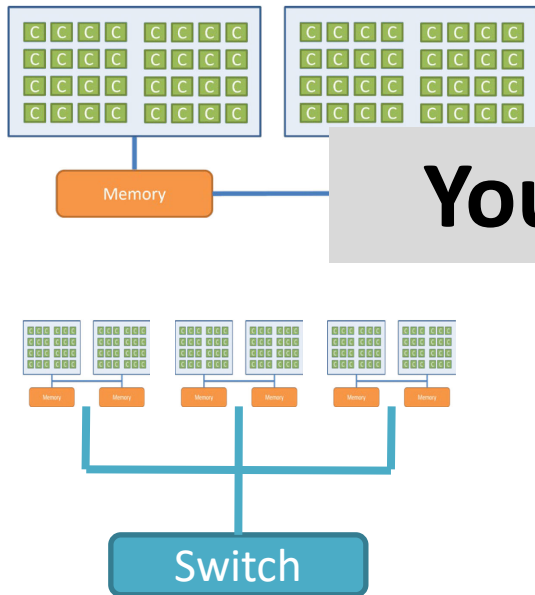


What About MPI+OpenMP Hybrid?

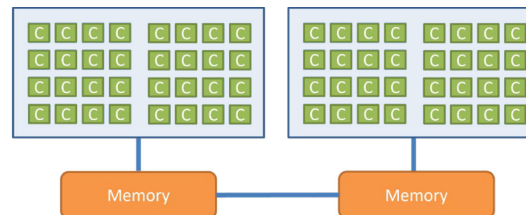
- Getting the benefits from both worlds?
- In theory, yes

Your mileage may vary! (well-written MPI programs might hurt the performance)

- Hybrid helps to
 - Reduce memory footprint
 - Extend scalability



Single Node Performance



QB-4 vs QB-3 (Node over Node)

	QB-4	QB-3
CPU frequency	2.6×10^9	2.4×10^9
CPU cores	64	48
Operation per cycle	32	32
Memory bandwidth	~115 GB/s	~48 GB/s
Interconnect	200 Gbps	100 Gbps

Node peak performance

QB-4: $64 \text{ cores/node} * 2.6 \times 10^9 \text{ cycles/second} * 32 \text{ flop/cycle} = 5.32 \times 10^{12} \text{ flops}$

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Theoretical speedup = 1.4

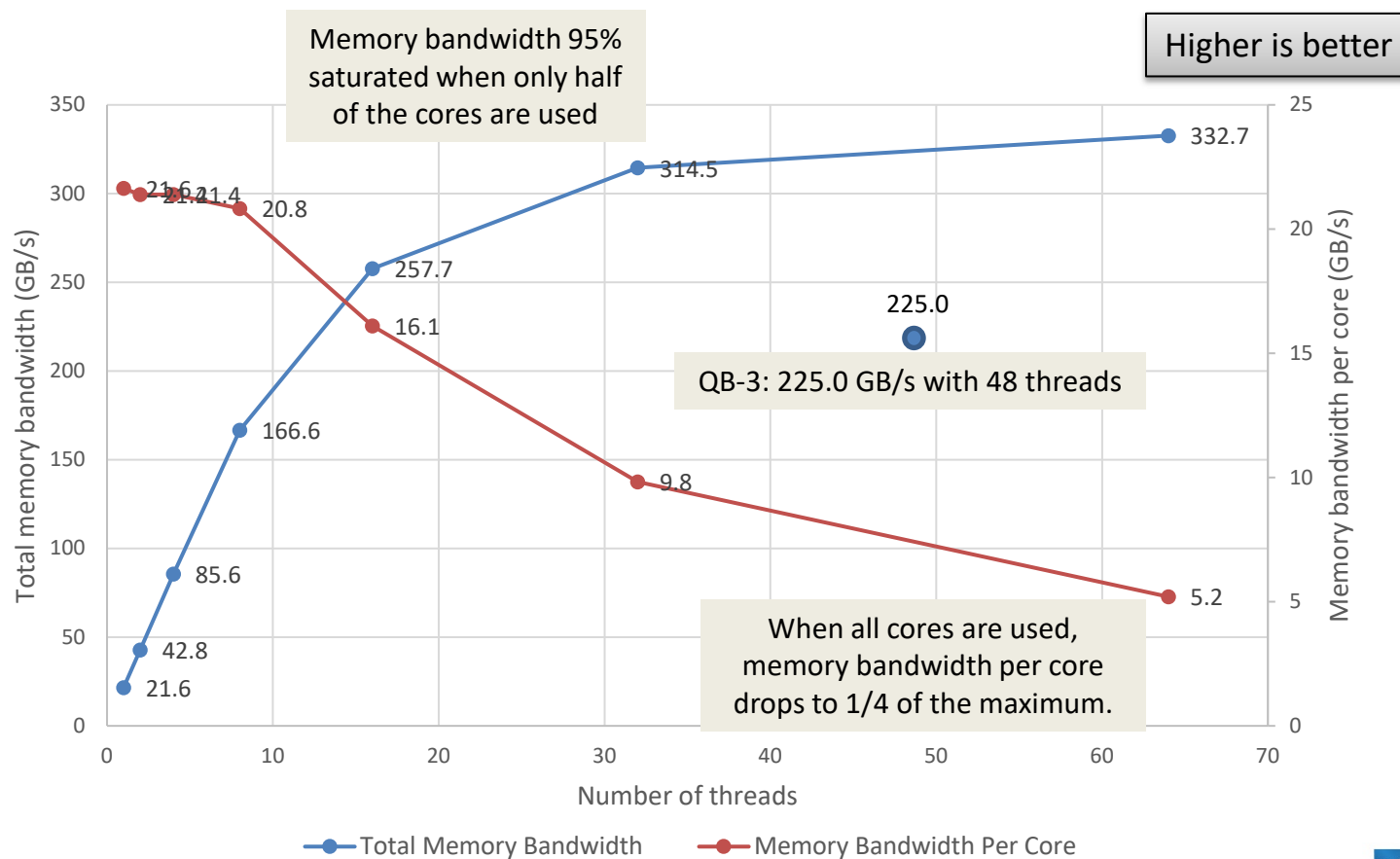


STREAM Benchmark

- The de facto industry standard benchmark in HPC domain for the measurement of sustainable **memory bandwidth** (in GB/s).



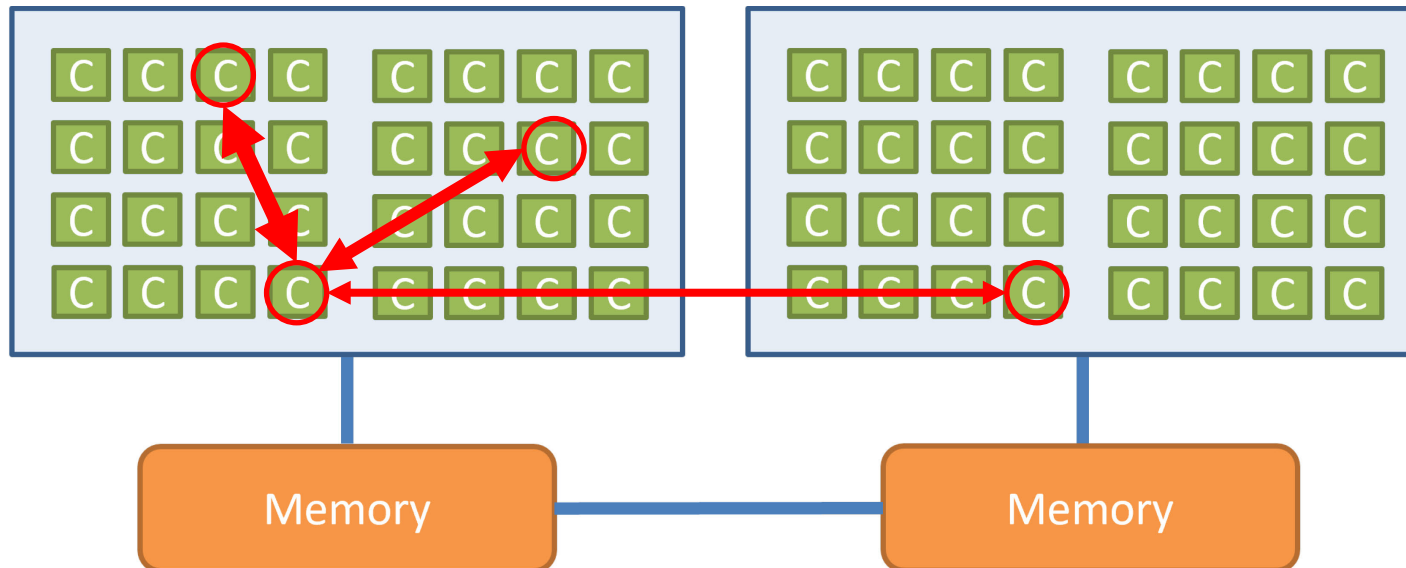
STREAM Benchmark - Results



STREAM 5.10
Array size = 160 MB
Intel 2021.5.0 with "-O3 -xCORE-AVX512"
OMP_PROC_BIND=spread



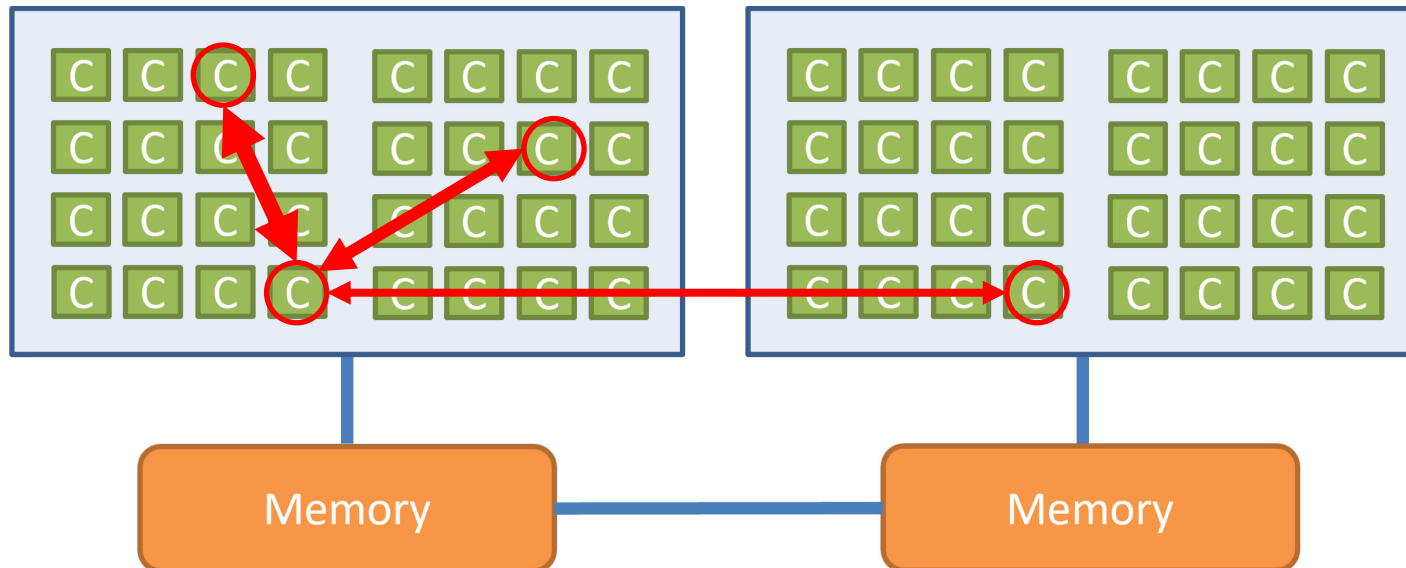
Thread Affinity



- The 64 cores on a SM-3 node are grouped into 4 sets.
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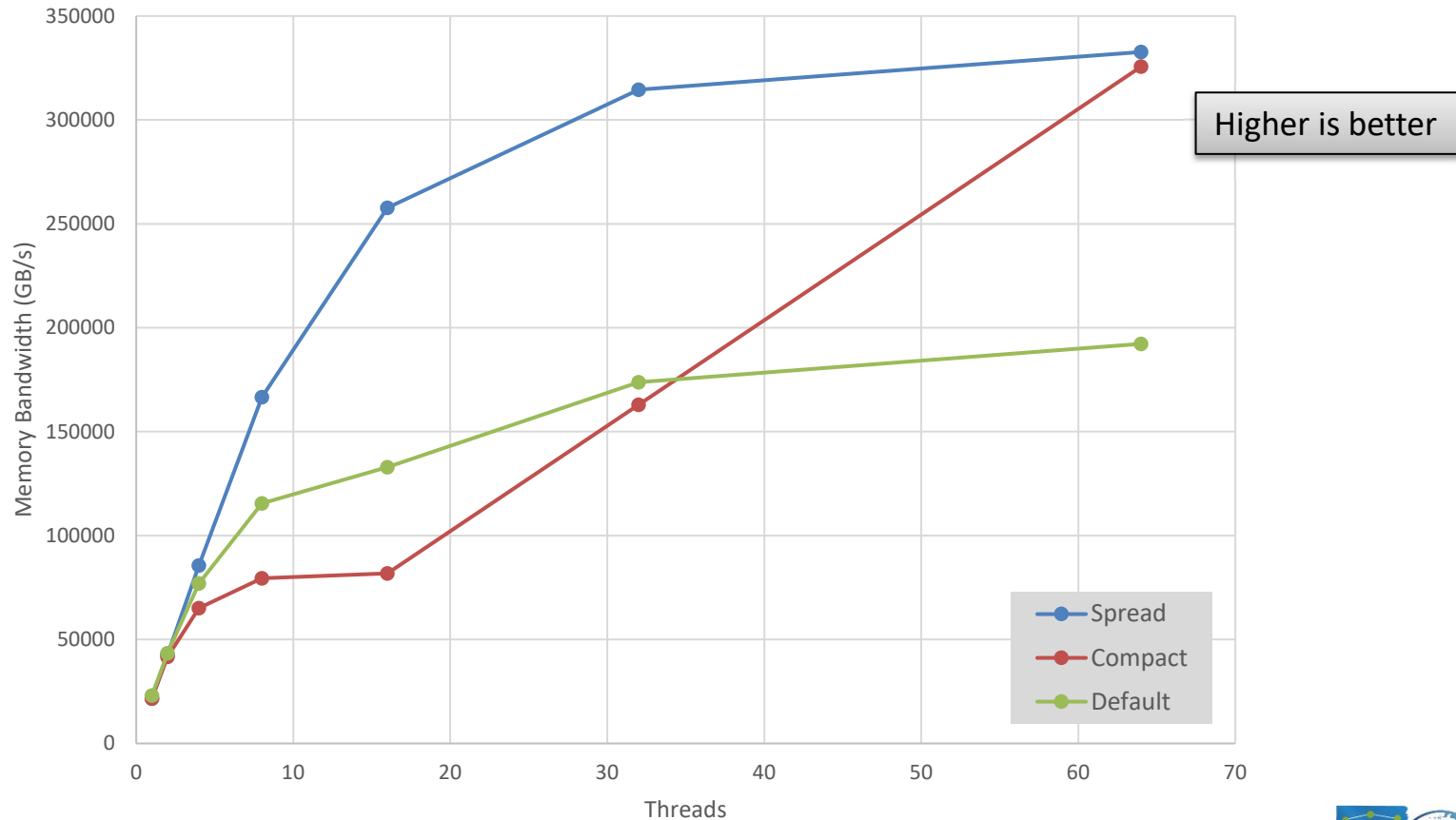
Thread Affinity



- For programs compiled with Intel compilers, use the `KMP_AFFINITY` environment variable to control thread placement/affinity
- The options are “none” (default), “disabled”, “balanced”, “compact”, and “scatter”.
- Use `OMP_PROC_BIND=spread` in place of “balanced”.



STREAM – Thread Affinity



STREAM 5.10
Array size = 160 MB
Intel 2021.5.0 with "-O3 -xCORE-AVX512 -qopt-zmm-usage=high"



HPL Benchmark

- High Performance Linpack
 - Standard benchmark for **CPU-bound** HPC applications
- Results
 - QB-4: 3847 GFLOPS per node
 - QB-3: 2452 GFLOPS per node
 - Speedup = 1.57 (compared to 1.4 theoretical)

CPU is well fed

HPCG Benchmark

- High Performance Conjugate Gradient
 - Standard benchmark for **memory-bound** HPC applications
- Results
 - QB-4: 55.0 GFLOPS per node
 - QB-3: 33.1 GFLOPS per node
 - Speedup: 1.66 (compared to 1.4 theoretical)

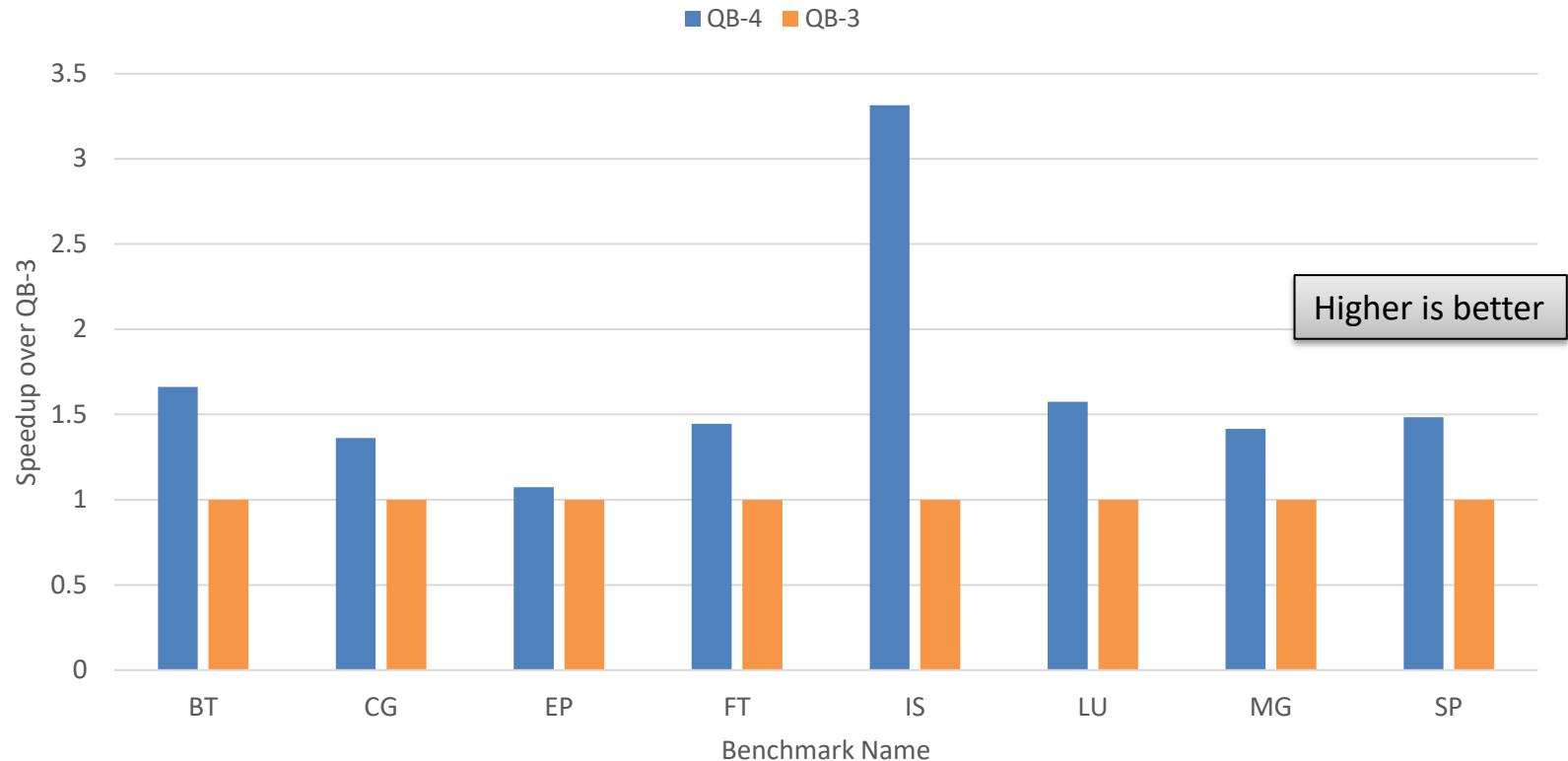
CPU is always hungry

NPB Benchmark Suite

- NAS Parallel Benchmarks
 - a small set of programs derived from computational fluid dynamics applications
- Five kernels and three pseudo-applications
 - IS - Integer Sort, random memory access
 - EP - Embarrassingly Parallel
 - CG - Conjugate Gradient, irregular memory access and communication
 - MG - Multi-Grid on a sequence of meshes, long- and short-distance communication, memory intensive
 - FT - discrete 3D fast Fourier Transform, all-to-all communication
 - BT - Block Tri-diagonal solver
 - SP - Scalar Penta-diagonal solver
 - LU - Lower-Upper Gauss-Seidel solver



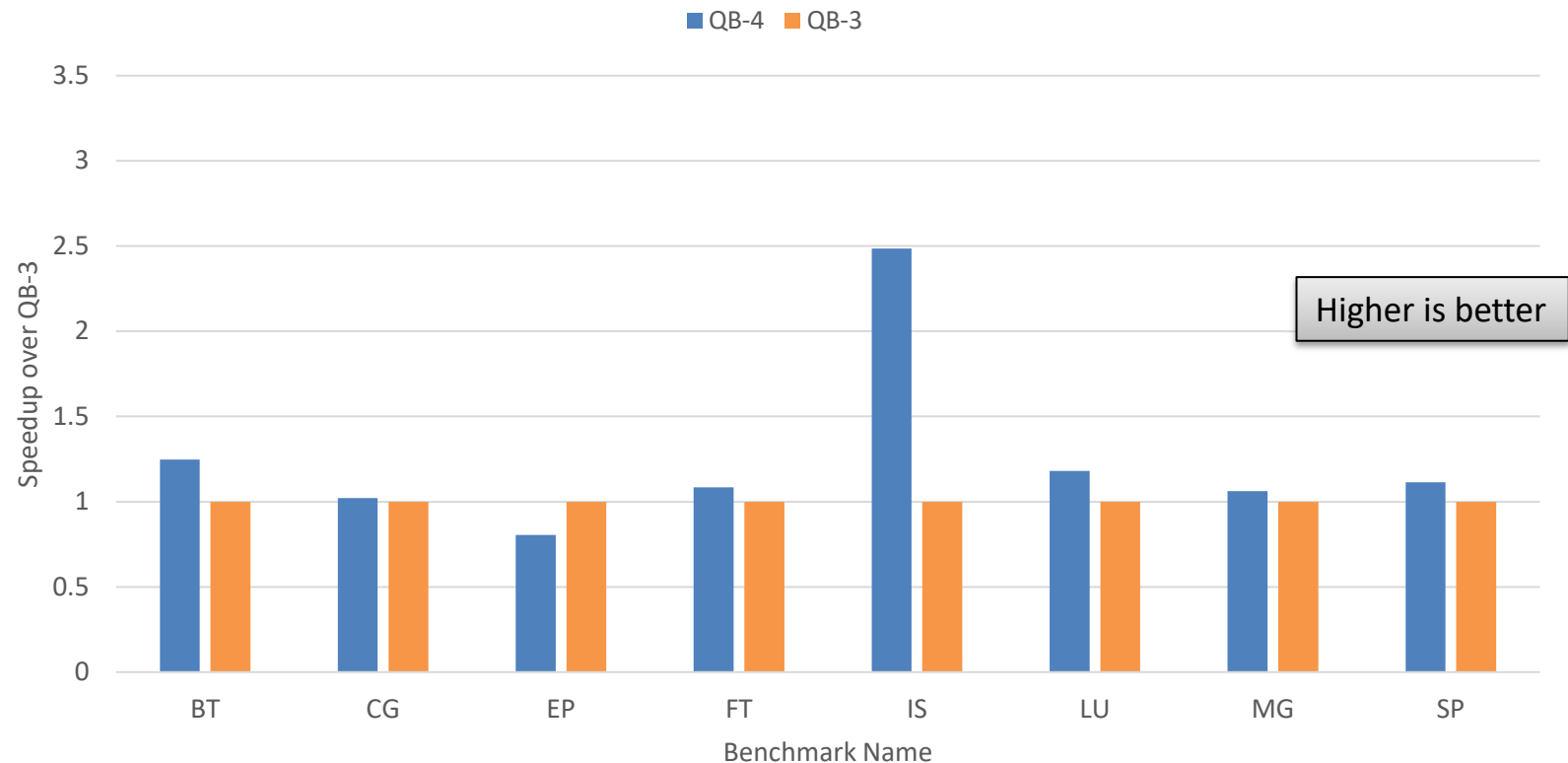
NPB Benchmarks – Node over Node



NPB 3.4.2, Class D
Intel 2021.5.0 with "-O3 -xCORE-AVX512"
KMP_AFFINITY=none



NPB Benchmarks – Core over Core



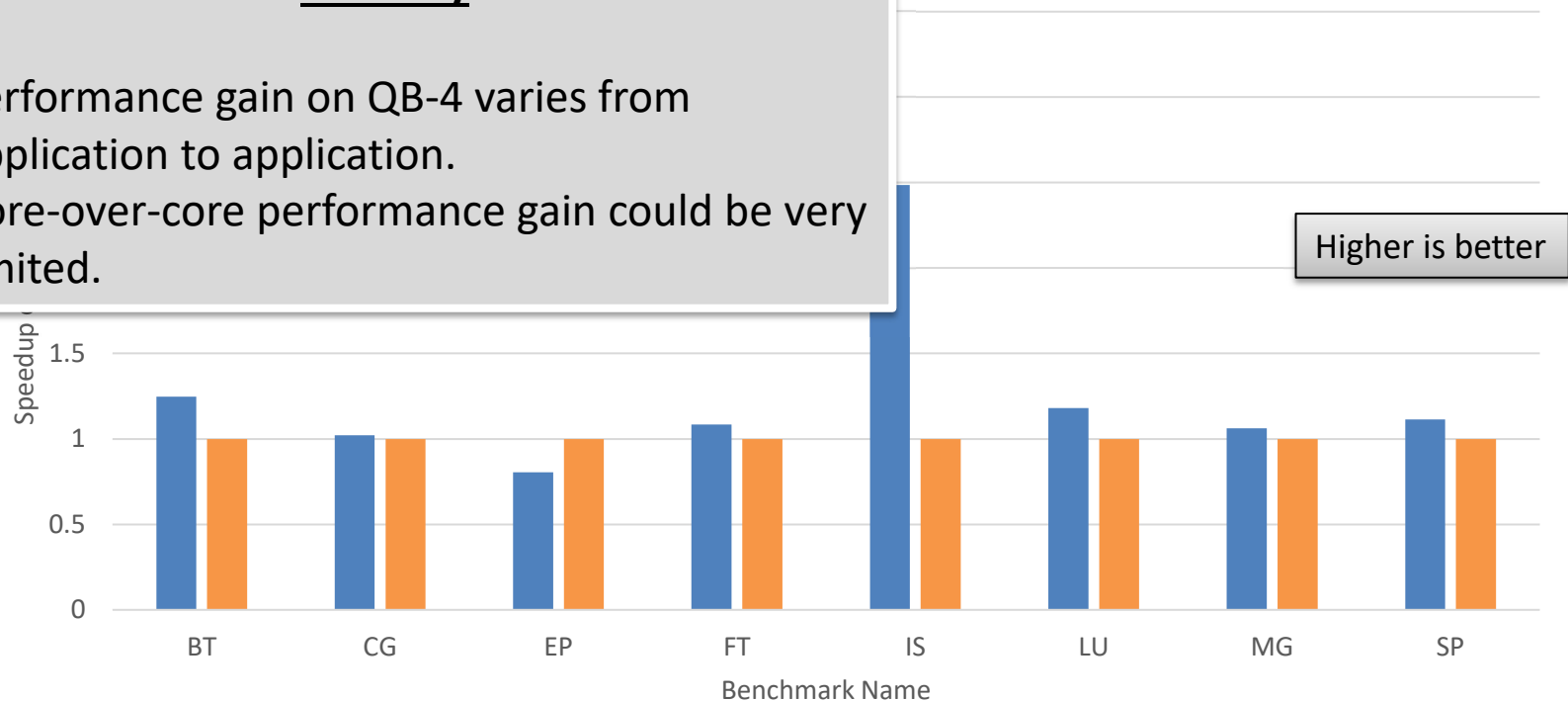
NPB 3.4.2, Class D
Intel 2021.5.0 with "-O3 -xCORE-AVX512"
KMP_AFFINITY=none



NPB Benchmarks – Core over Core

Takeway

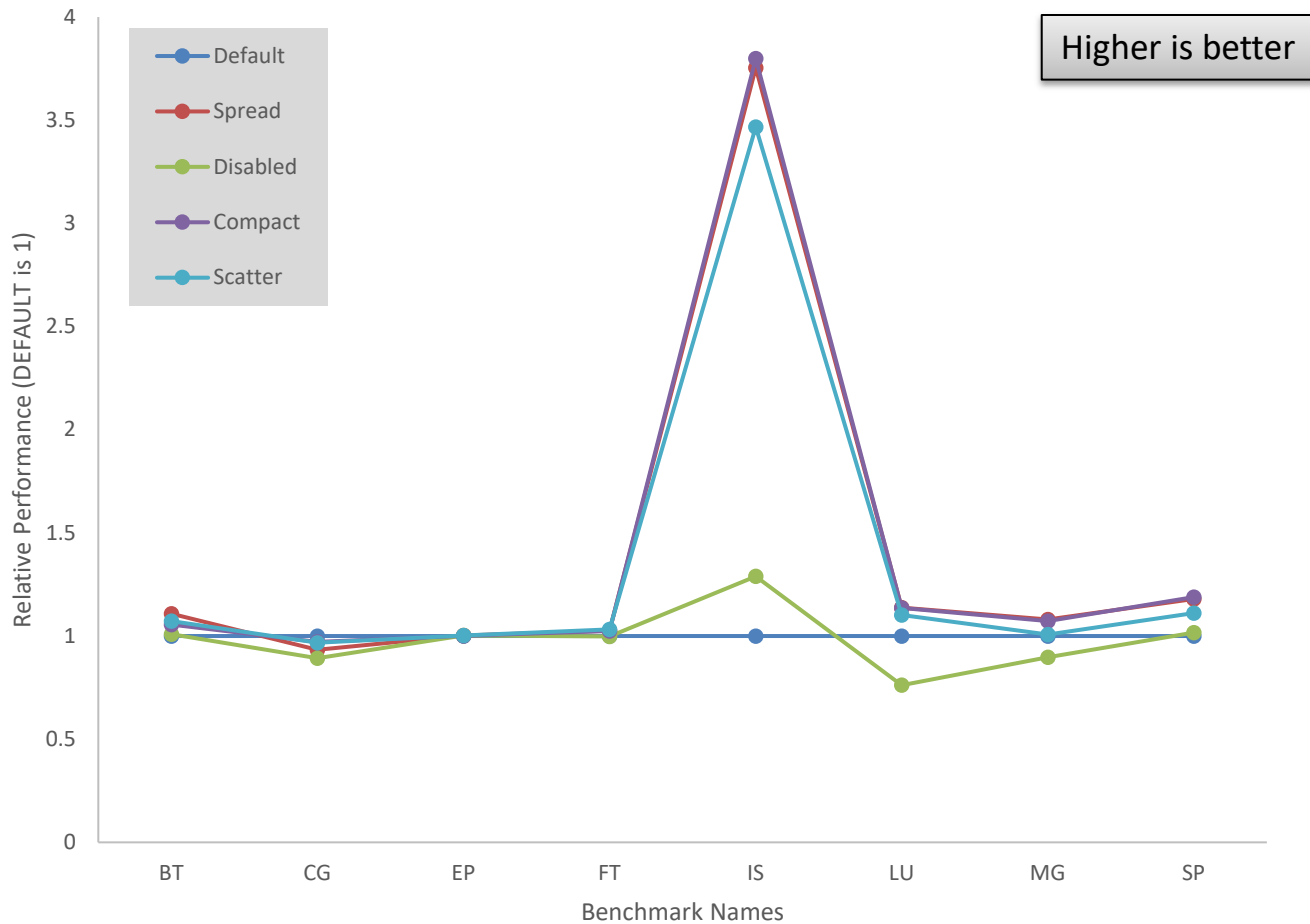
- Performance gain on QB-4 varies from application to application.
- Core-over-core performance gain could be very limited.



NPB 3.4.2, Class D
Intel 2021.5.0 with "-O3 -xCORE-AVX512"
KMP_AFFINITY=none



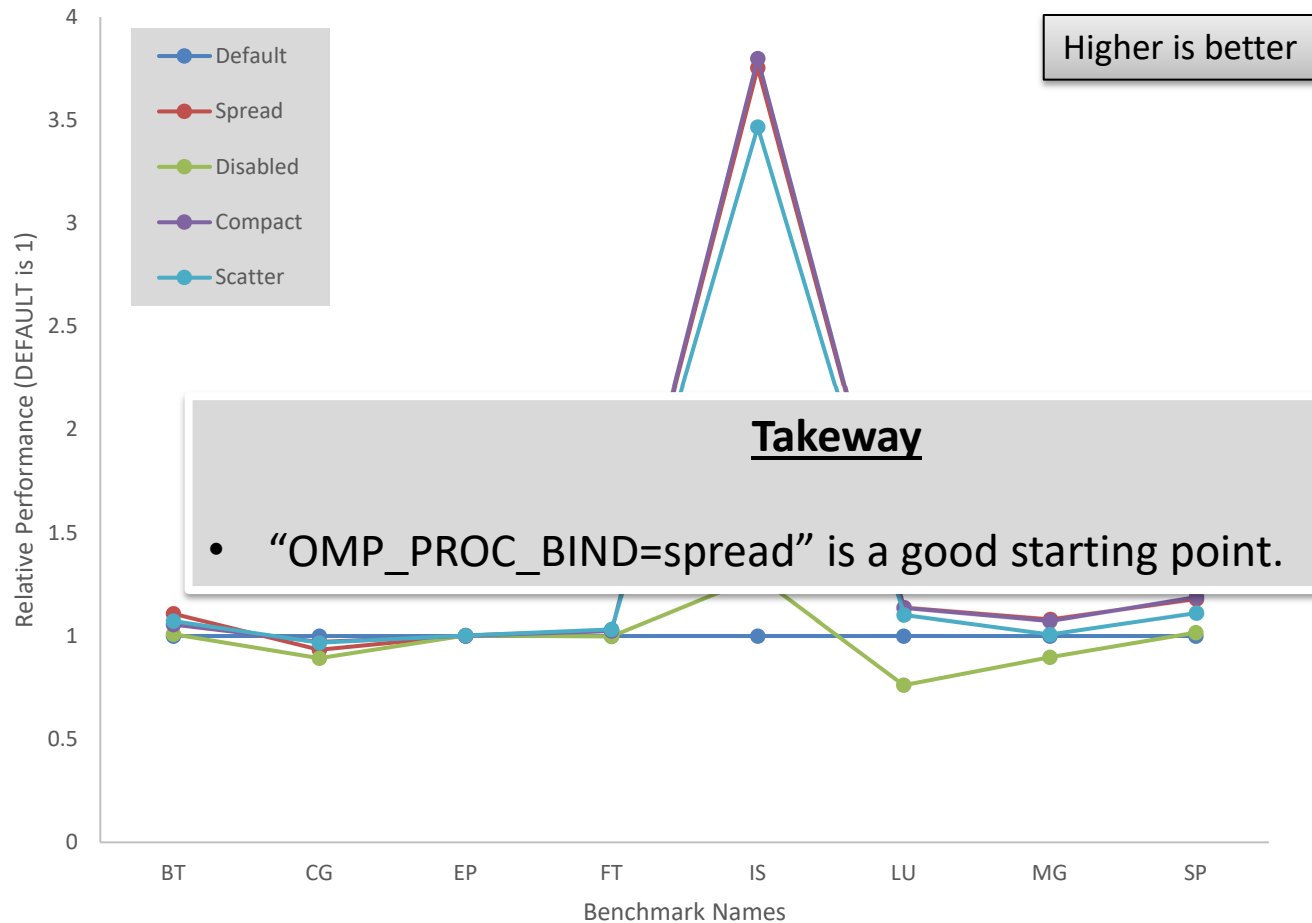
NPB Results – Thread Affinity



NPB 3.4.2, Class E
Intel 2021.5.0 with "-O3 -xCORE-AVX512"



NPB Results – Thread Affinity

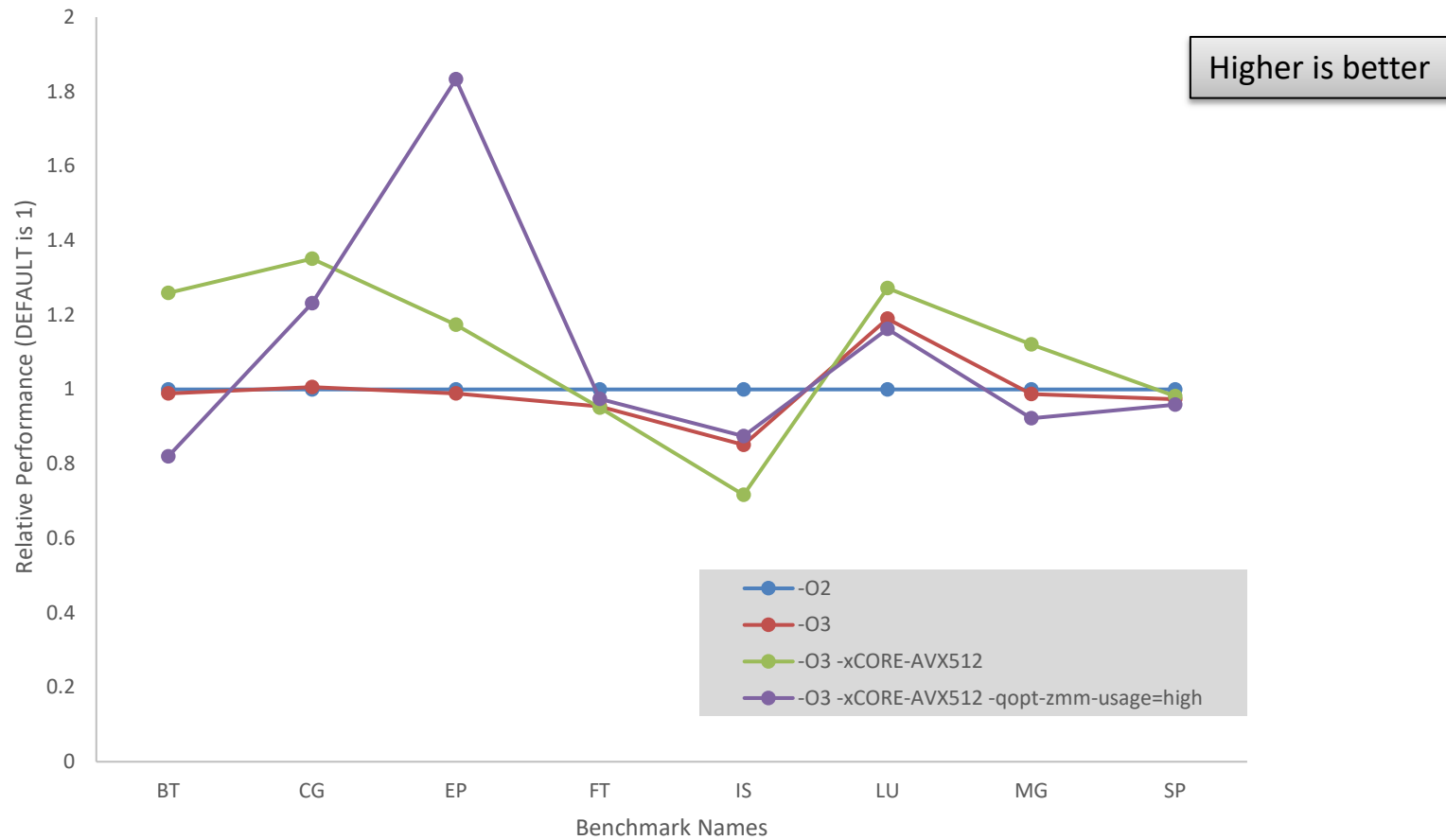


Compiler Flags (Intel)

- -O2, -O3
 - Generic, aggregated optimization flags
- -xCORE-AVX512
 - Turns on optimization for the Ice Lake (and SkyLake/Cascade Lake) processor
- -march=icelake-server
 - Turns on optimization specifically for Ice Lake
- -qopt-zmm-usage=high
 - Improves performance for some codes



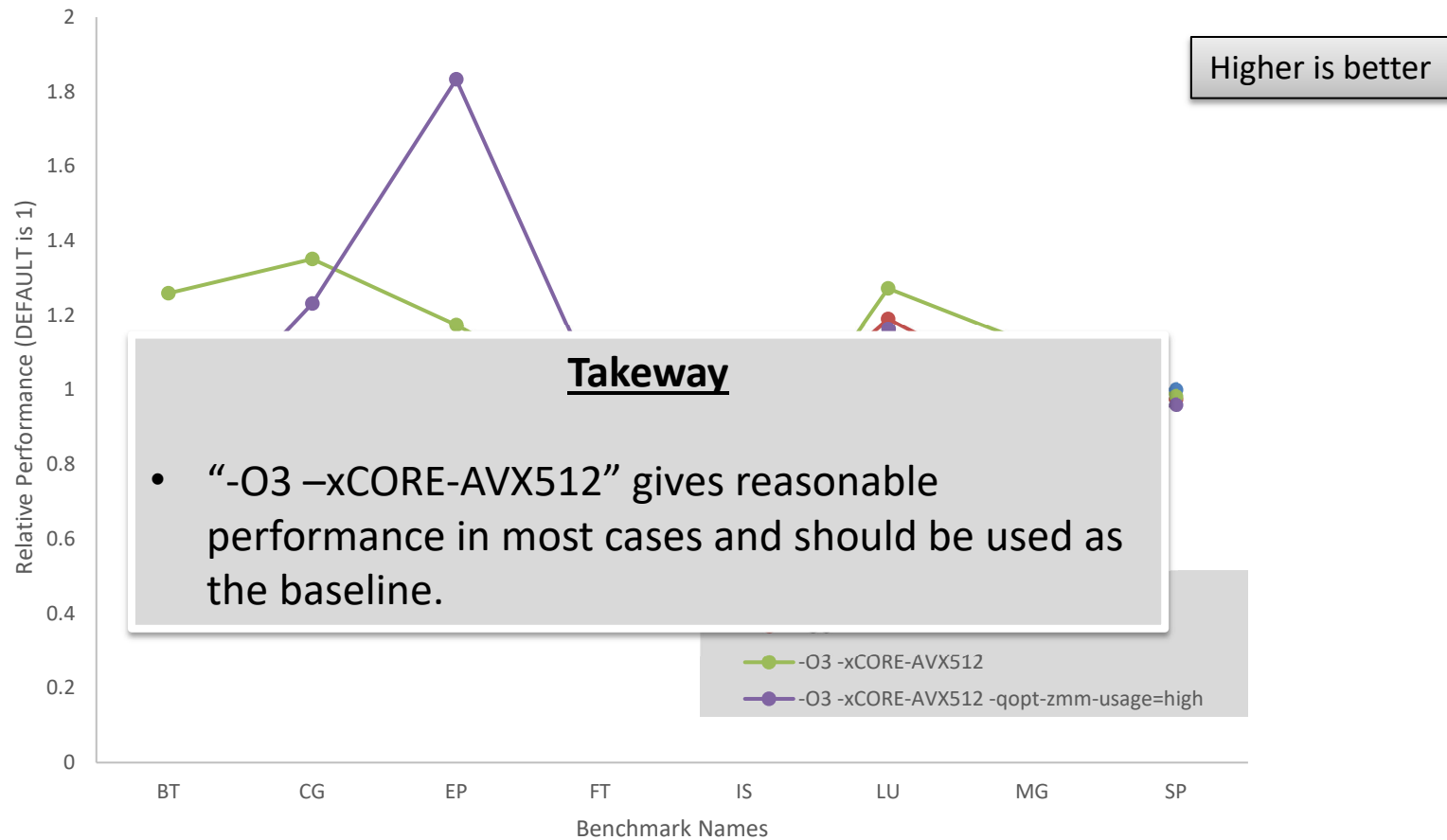
NPB Results – Compiler Flags



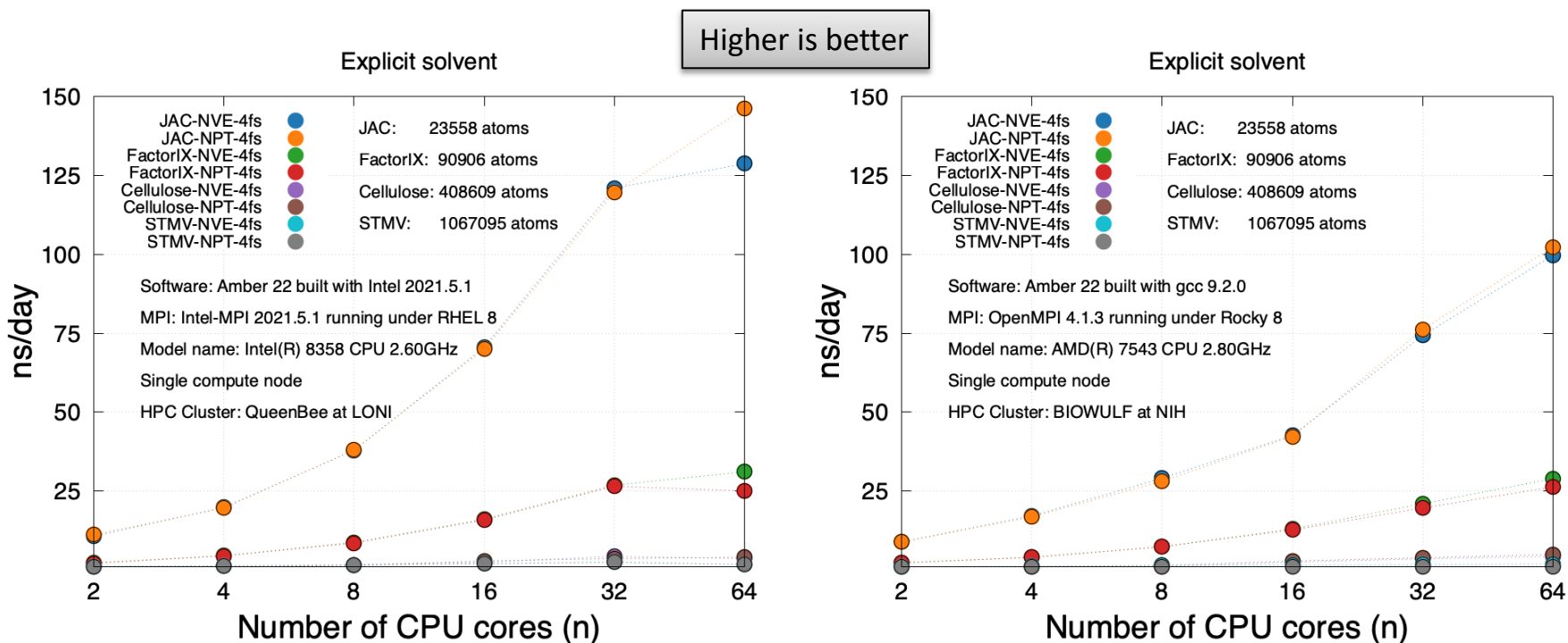
NPB 3.4.2, Class E
Intel 2021.5.0
KMP_AFFINITY=default



NPB Results – Compiler Flags



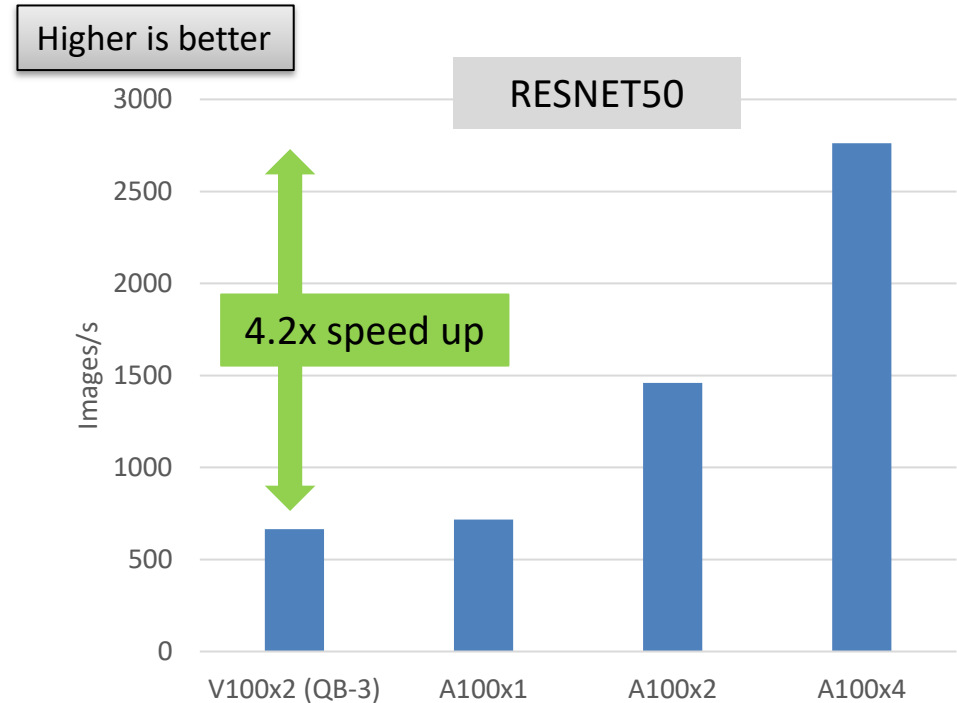
Amber 22



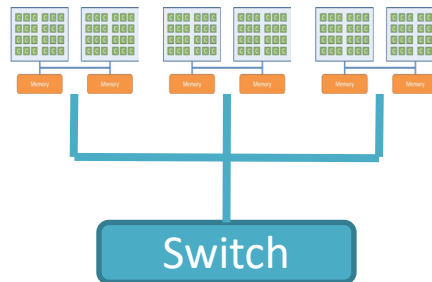
GPU Performance

GPU	QB-3	QB-4
Model	V100 PCIe	A100 PCIe
On-board memory	32GB	80GB
Processing power (DP)	7 TFLOPS	9.7 TFLOPS
NVLink	No	Yes
InterGPU bandwidth	~20 GB/s	~520 GB/s*

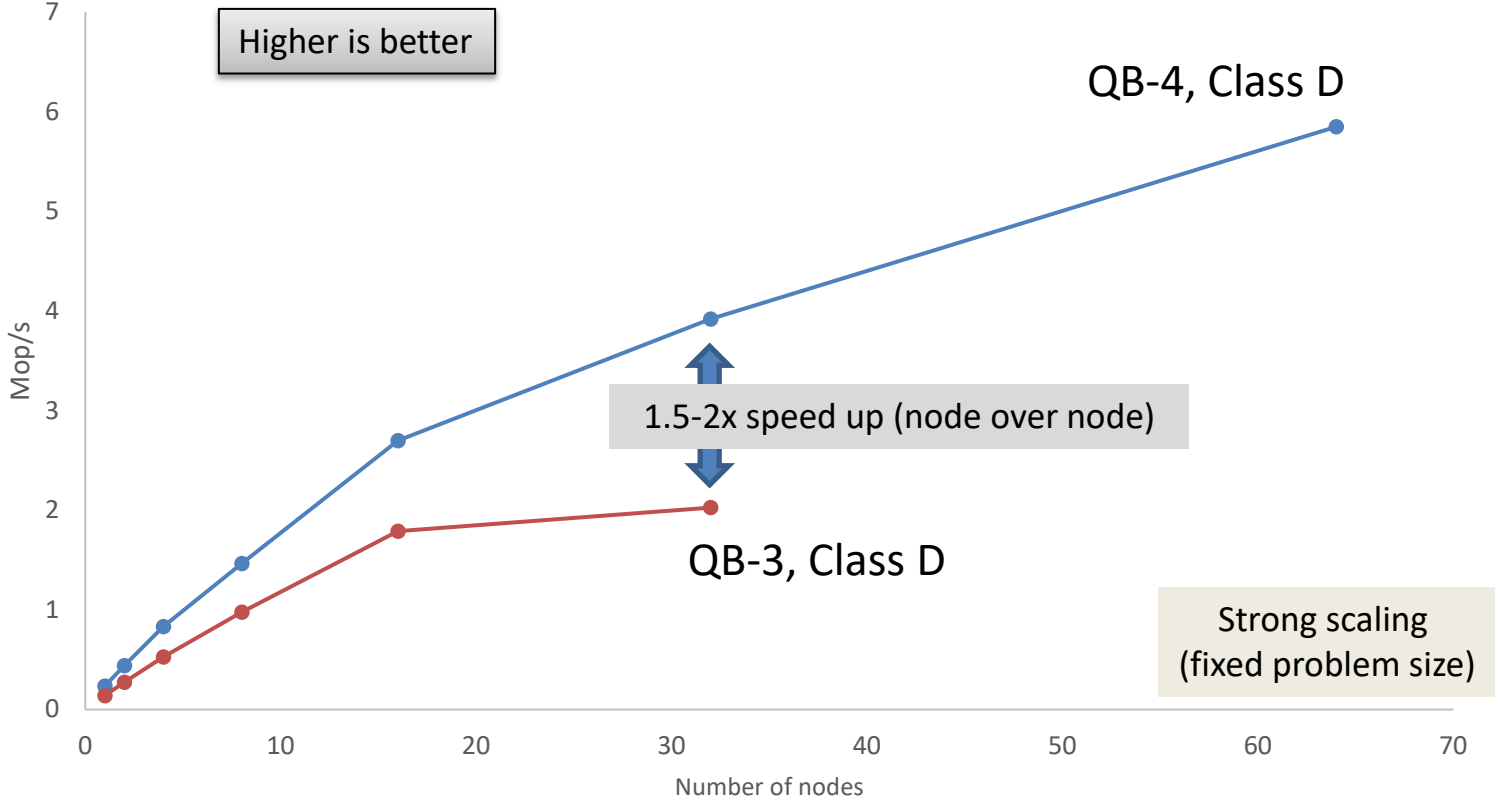
* On nodes with 4 GPU's, this is the bandwidth between device 0 and 1, and device 2 and 3



Multi-node Performance



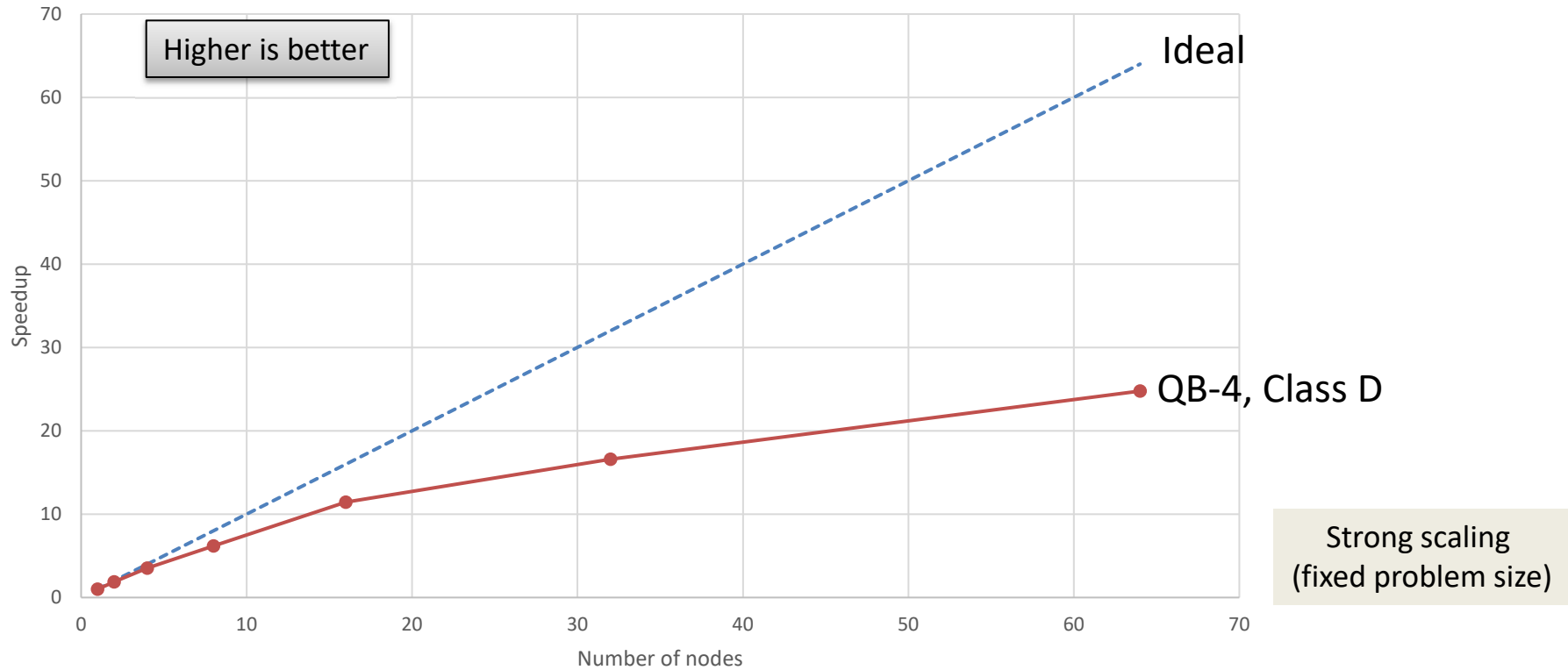
Pure MPI - NPB LU Benchmark



NPB 3.4.2, Class D
Intel MPI 2021.5.1
Intel 2021.5.0 with "-O3 -xCORE-AVX512"



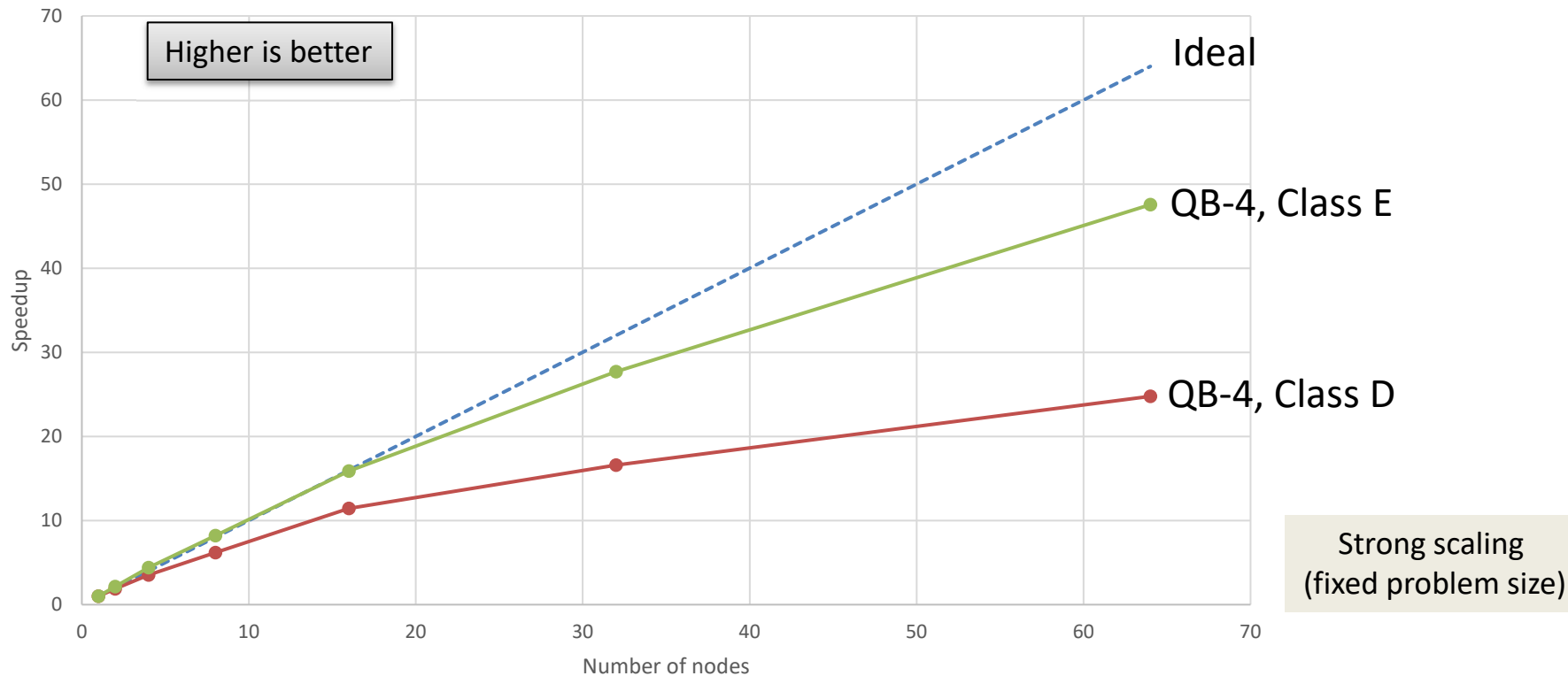
Pure MPI - NPB LU Benchmark



NPB 3.4.2, Class D and E
Intel MPI 2021.5.1
Intel 2021.5.0 with "-O3 -xCORE-AVX512"



Pure MPI - NPB LU Benchmark

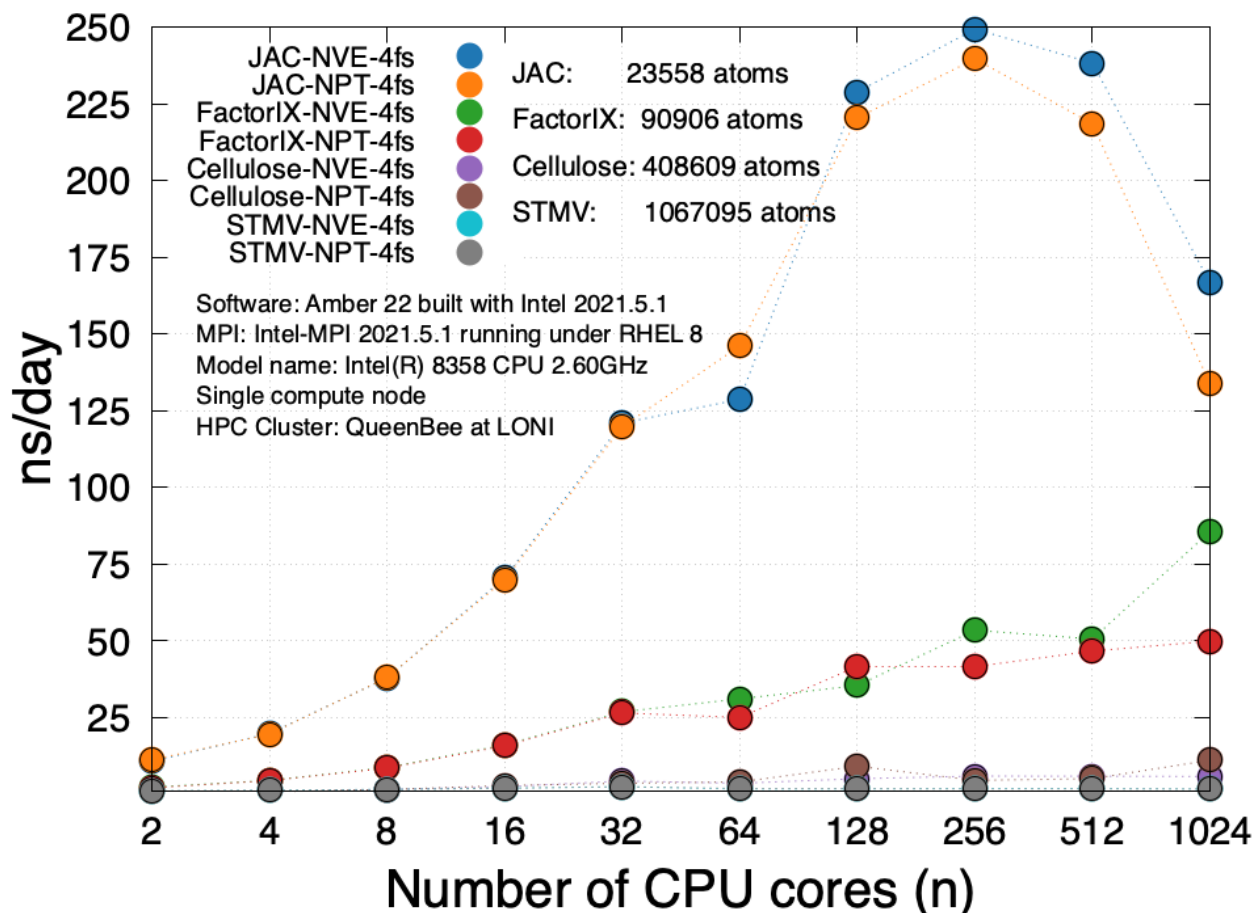


NPB 3.4.2, Class D and E
Intel MPI 2021.5.1
Intel 2021.5.0 with "-O3 -xCORE-AVX512"



Pure MPI – Amber 22

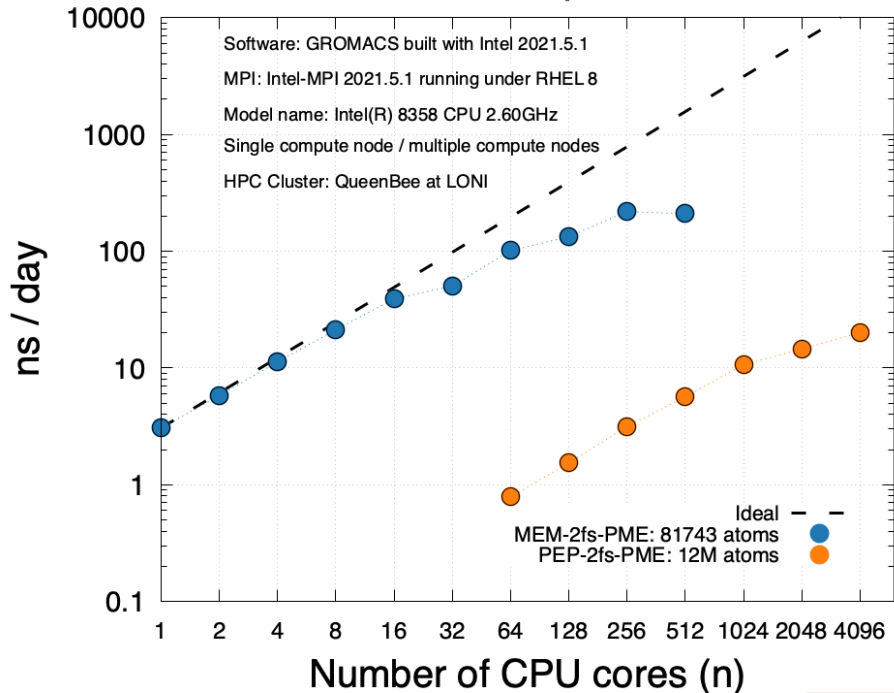
Explicit solvent



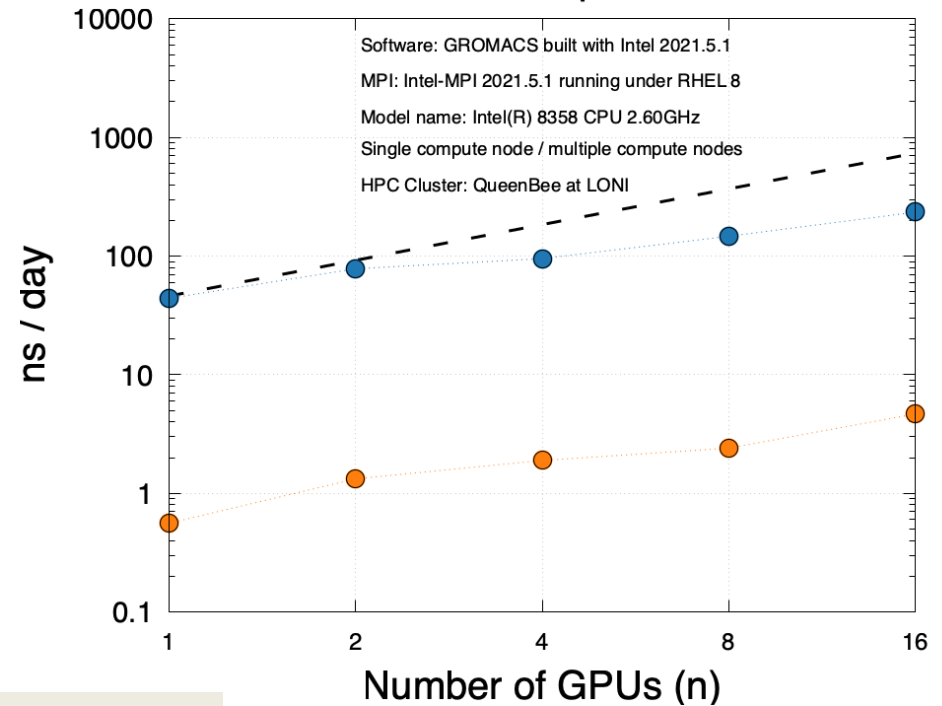
Pure MPI - GROMACS

Higher is better

Number of compute nodes



Number of compute nodes

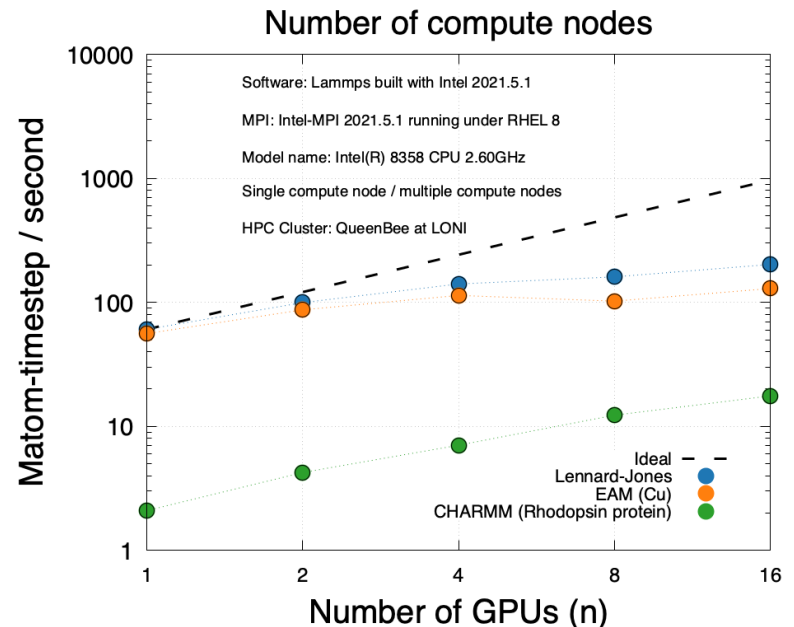
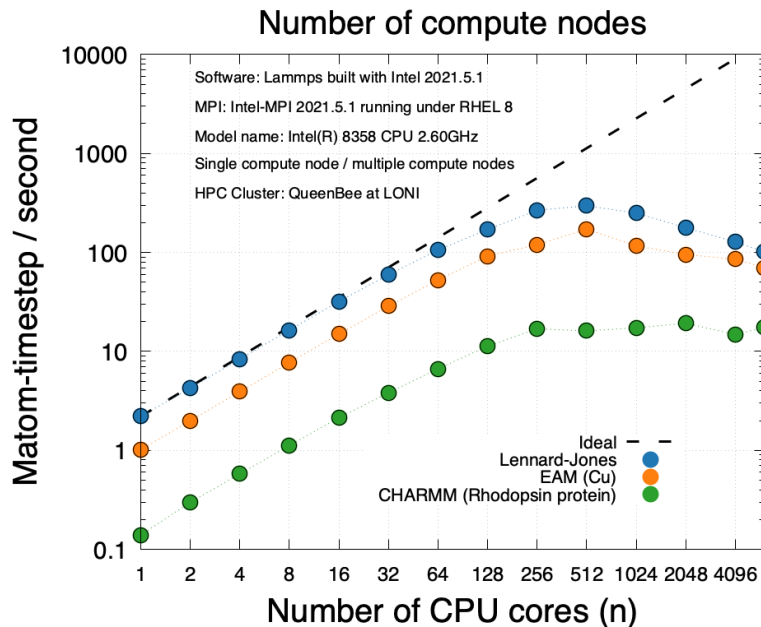


Strong scaling
(fixed problem size)



Pure MPI – LAMMPS

Higher is better

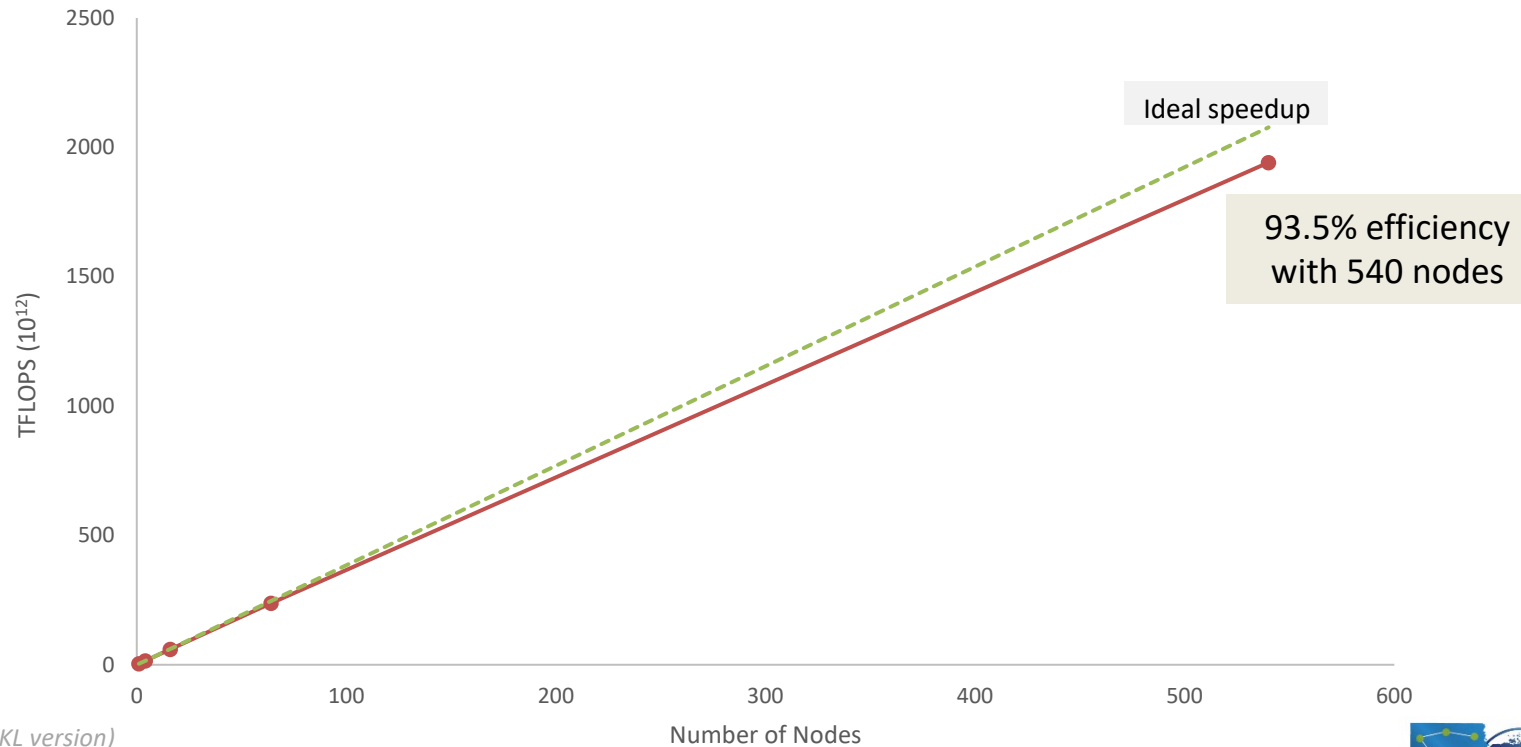


Strong scaling
(fixed problem size)



Hybrid – HPL

Weak scaling (problem size increases with core count)
1 MPI process per node * 64 threads per MPI process

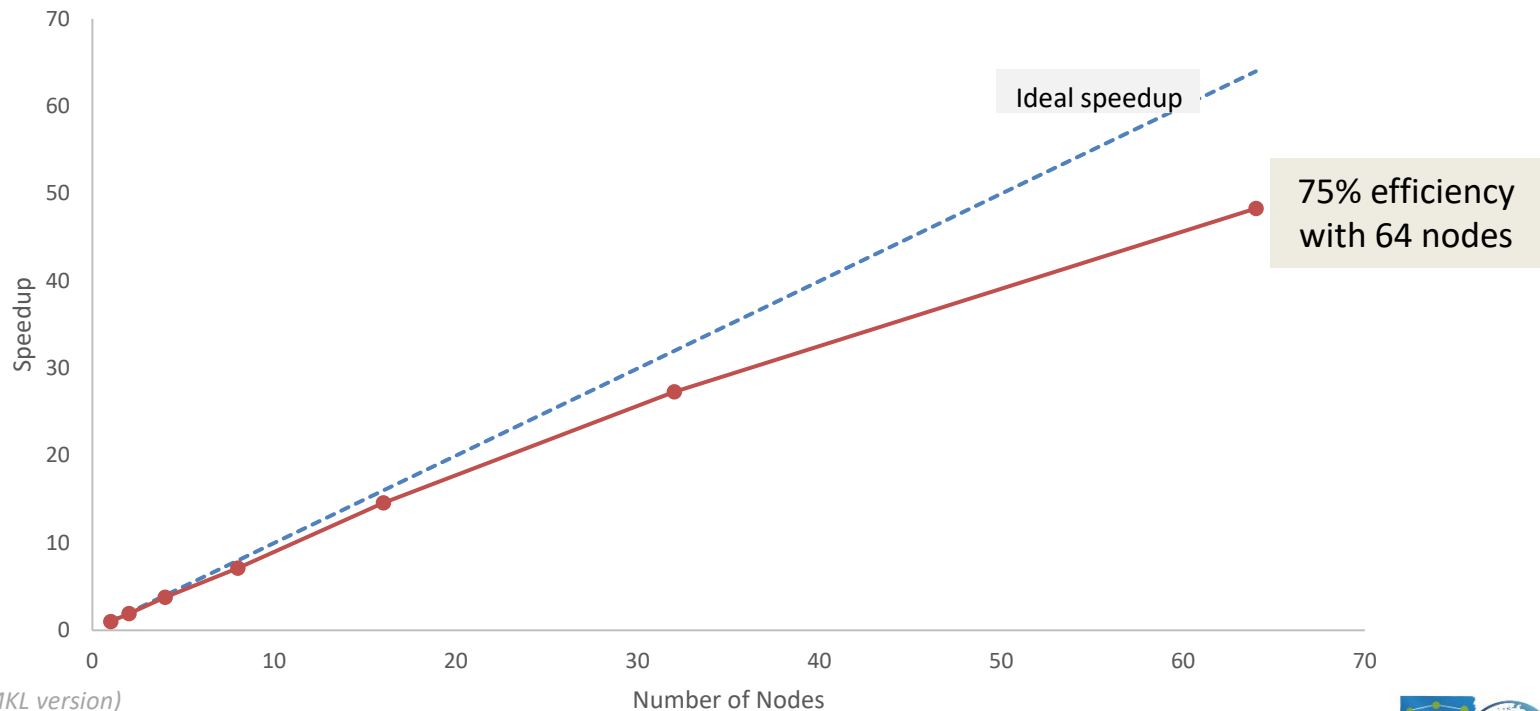


HPL 2.3 (Intel MKL version)
Problem size = 90% installed memory
Intel MPI 2021.5.1
Intel 2021.5.0 with "-O3 -xCORE-AVX512 -qopt-zmm-usage=high"



Hybrid - HPCG

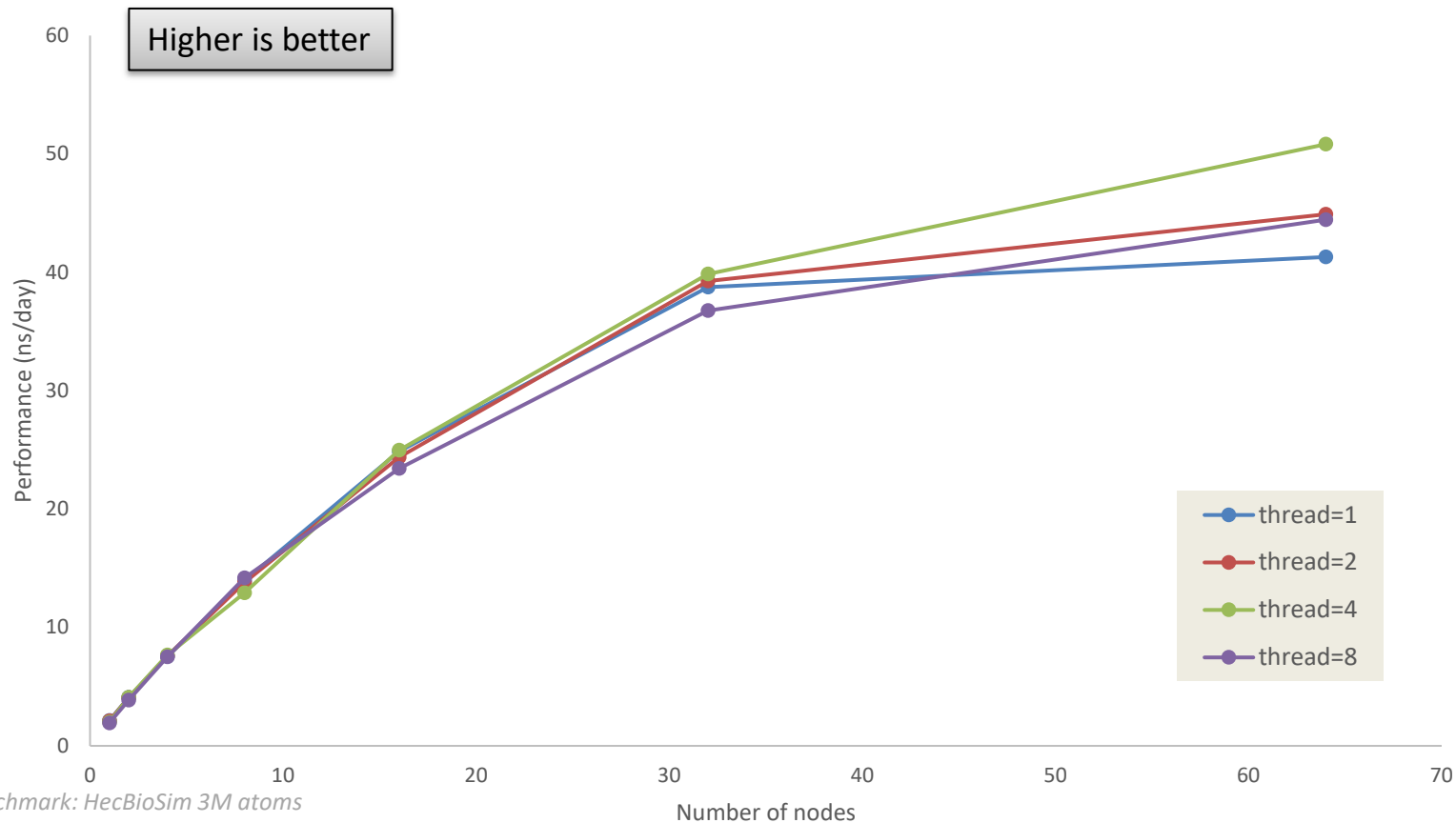
Weak scaling (problem size increases with core count)
1 MPI process per node * 64 threads per MPI process



HPCG 3.0 (Intel MKL version)
Problem size = 336 336 336
Intel MPI 2021.5.1
Intel 2021.5.0 with "-O3 -xCORE-AVX512 -qopt-zmm-usage=high"



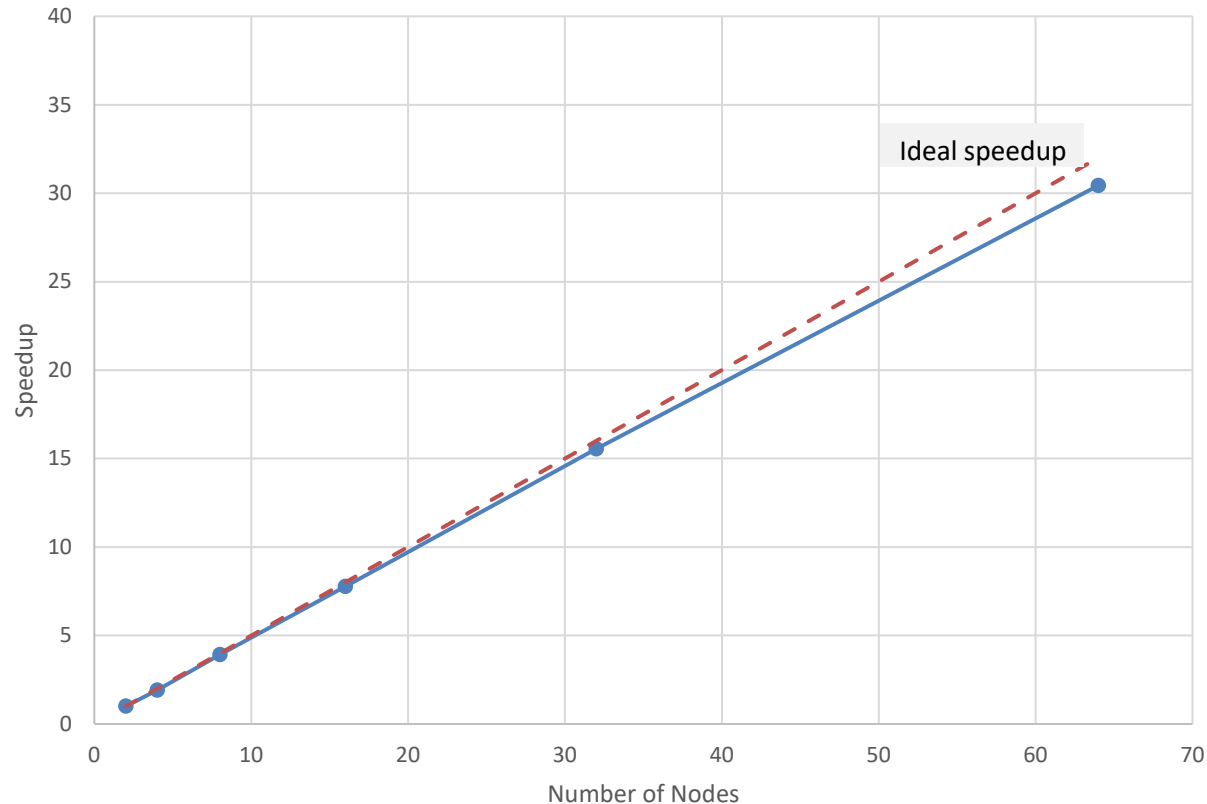
Hybrid - GROMACS



Benchmark: HecBioSim 3M atoms
GROMACS
Intel MPI 2021.5.1
Intel 2021.5.0
KMP_AFFINITY=default



GPU Scaling – GPT-2 Training



GPT-2 (124M) model

Python 3.10.12

Pytorch 2.3.0

Transformer 4.41.2

CUDA 12.4.1

Configuration: <https://github.com/karpathy/llm.c/discussions/481>



I/O Consideration

- You want to avoid letting your program accesses to disk excessively
 - Reading/writing hundreds of GBs to checkpoint or output files frequently
 - Running with thousands of MPI tasks all reading/writing individual files
- What you should and should not do
 - Avoid writing intermediate/checkpoint files unless necessary
 - Look for and use options that allow one or a few big files instead of files per process
 - Reduce the frequency of writing output files
 - Do not use /home for productive jobs – use /work instead



Takeaways (1)

- In most cases, your application will run faster and scale better on QB-4 (compared to QB-3)
- That being said, how much faster depends on a lot of factors
- You need to run your own experiments before making a (educated) decision whether or not switch to QB-4



Takeaways (2)

- Baseline
 - Use “-O3 -xCORE-AVX512” to compile
 - The default settings work reasonably well in most cases
- Serial (single core) programs
 - The performance gain can be limited
- OpenMP programs
 - Use KMP_AFFINITY=balanced as baseline and try different settings
- MPI programs
 - Find the optimal number of nodes by running scaling tests
 - Remember the scaling behavior depends on the problem size
- Hybrid programs
 - They do not always perform and scale better than MPI programs, especially for small problems and low node count
 - The optimal number of threads (and affinity) could be tricky to find and varies from application to application



Takeaways (2)

- Baseline
 - Use “-O3 -xCORE-AVX512” to compile
 - The default settings work reasonably well in most cases
- Serial (single core) programs
 - The performance gain can be limited
- OpenMP
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 - Remember the scaling behavior depends on the problem size
- Hybrid programs
 - They do not always perform and scale better than MPI programs, especially for small problems and low node count
 - The optimal number of threads (and affinity) could be tricky to find and varies from application to application

Avoid excessive I/O!!!



Takeaways (2)

- Baseline
 - Use “-O3 -xCORE-AVX512” to compile
 - The default settings work reasonably well in most cases
- Serial (single core) programs
 - The performance gain can be limited
- OpenMP
 - Use k
- MPI programs
 - Find the optimal number of nodes by running scaling tests
 - Remember the scaling behavior depends on the problem size
- Hybrid programs
 - They do not always perform and scale better than MPI programs, especially for small problems and low node count
 - The optimal number of threads (and affinity) could be tricky to find and varies from application to application

If you need help, let us know!

