

Parallelizing The Matrix Multiplication





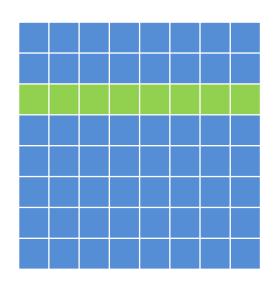


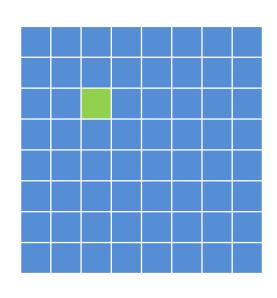
Serial version











 A_{md}

X

Χ

 $\boldsymbol{B}_{\text{dn}}$

=

=

 C_{mn}

$$c_{i,j} = \sum_{k=1}^{d} a_{i,k} \cdot b_{k,j}$$







```
//Read and validate command line arguments
Read M,N,D from the command line
```

//Initialize the arrays

For all elements of A and B

initial value = function (i, j)

$$a_{i,j} = i + j$$

$$b_{i,j} = i * j$$

// Matrix multiplication
For each C (i,j)
// Take the inner product of row i of A and column j of B
For each A (i,k) and B(k,j)
 C (i,j) = C (i,j) + A (i,k) * B(k,j)





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Anything else?







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$$a_{i,j} = i + j$$

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How do we know the result is correct?

Result validation is very important!







$$c_{i,j} = \sum_{k=1}^{N} a_{i,k} \cdot b_{k,j}$$

$$= \sum_{k=1}^{N} (i+k) \cdot j \cdot k$$

$$= \sum_{k=1}^{N} (ijk + jk^{2})$$

$$= ij \sum_{k=1}^{N} k + j \sum_{k=1}^{N} k^{2}$$

Assuming A, B and C are all N x N square matrices



We can use this formula to validate the result from the program





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//Validate the result

Print out an element of C and compare it to the value given by the formula







Serial Program Details

- A, B and C are all N x N square matrices
- Take input arguments
 - N: dimension of the matrices
 - $-i_{peek}$, j_{peek} : indices of the element used for result validation
- Values of A and B:

$$a_{i,j} = i + j$$

$$b_{i,j} = i * j$$

- Output
 - How much time it takes (performance measurement)
 - The value of $C(i_{peek}, j_{peek})$ and the value given by the formula







Parallel version







Writing a parallel program step by step

- Step 1. Start from serial programs as a baseline
 - Something to check correctness and efficiency against
- Step 2. Analyze and profile the serial program
 - Identify the "hotspot"
 - Identify the parts that can be parallelized
- Step 3. Parallelize code incrementally
- Step 4. Check correctness of the parallel code
- Step 5. Iterate step 3 and 4







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Which parts can and should be parallelized?







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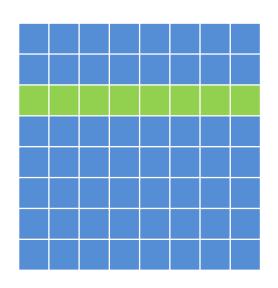
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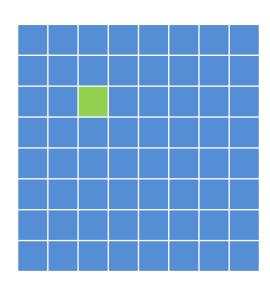
Which parts can and should be parallelized?











 A_{nn}

X

Χ

 \mathbf{B}_{nn}

=

=

 C_{nn}

$$c_{i,j} = \sum_{k=1}^{n} a_{i,k} \cdot b_{k,j}$$







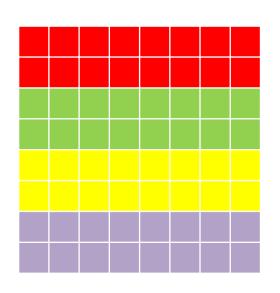
Some Considerations

- Decomposition
 - 1-D or 2-D
- Data distribution
 - Each process owns the entire matrices, but only performs calculation on a part of them, or
 - Each process only owns the sub-matrices that it is going to process

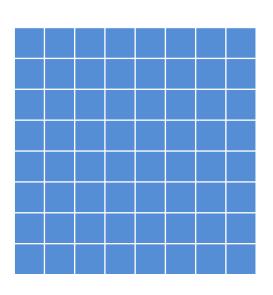




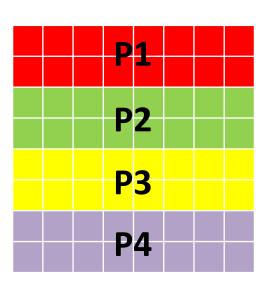




Χ



=



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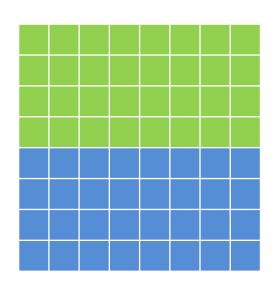
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 C_{nn}

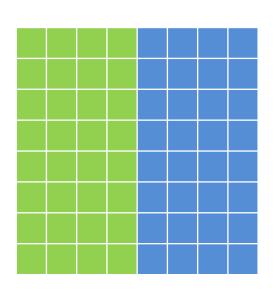




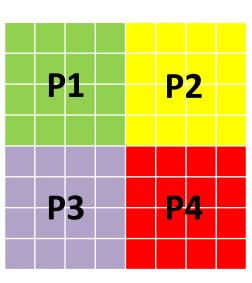




X



=



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 \mathbf{B}_{nn}

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=

 C_{nn}





Optimization Conderations

- Avoid data movement as much as possible (i.e. increase the amount of computation done relative to the amount of data moved)
 - True for both serial and parallel programs
 - For parallel programs, data movement means data communication between host and device (GPU) or between different nodes (distributed memory systems)
- Reduce the memory footprint
- When developing a parallel program, it's important to know what to expect in terms of speedup and scaling





Cannon's Algorithm







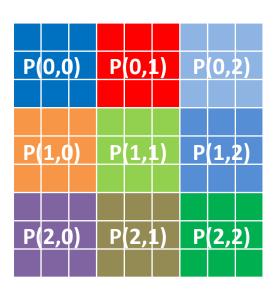
Cannon's Algorithm

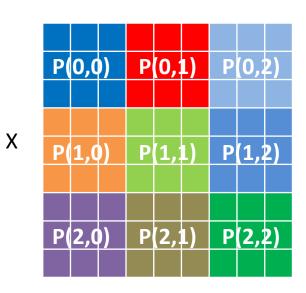
- Assume
 - the number of processes p is a perfect square
 - the matrices are N x N square
- Arrange the processes into a 2-D \sqrt{p} x \sqrt{p} process grid
 - For each matrix, each process is assigned with a block of $N/\sqrt{p} \times N/\sqrt{p}$

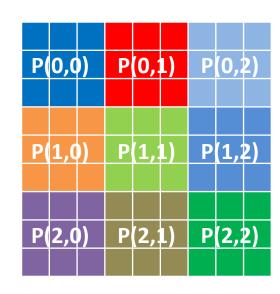












 A_{nn}

X

 B_{nn}

=

=

nn

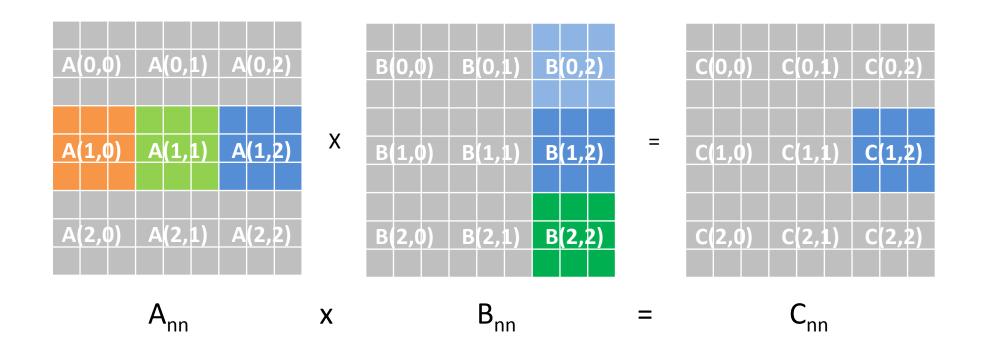
$$c_{i,j} = \sum_{k=1}^{N} a_{i,k} \cdot b_{k,j}$$

Working by elements









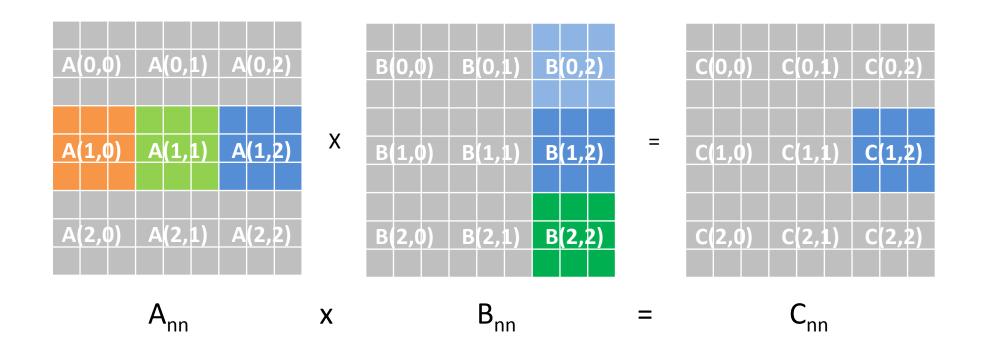
$$C(1,2) = A(1,0) \times B(0,2) + A(1,1) \times B(1,2) + A(1,2) \times B(2,2)$$



Working by blocks







 $C(1,2) = A(1,0) \times B(0,2) + A(1,1) \times B(1,2) + A(1,2) \times B(2,2)$

Three phases: phase1 phase2 phase3



The multiplication is completed in \sqrt{p} phases





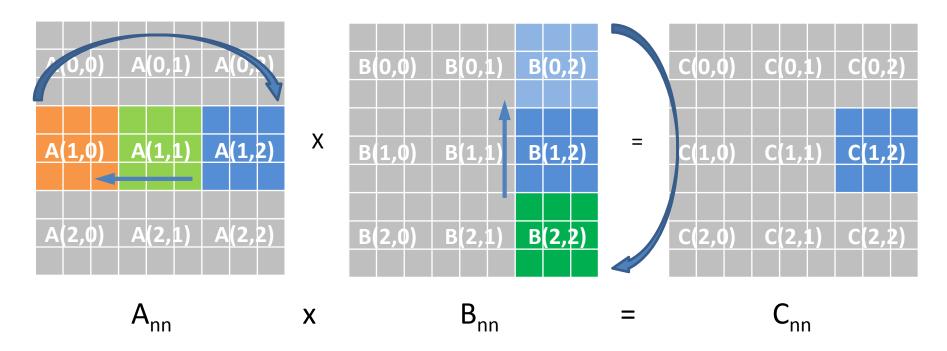
Cannon's Algorithm

- Two stages
 - Skew the matrices so everything aligns properly
 - Shift row i of A by i columns to the left
 - Shift column j of B by j rows to the up
 - Shift and multiply
 - Each process calculate the local product and add into the accumulated sum
 - Shift A by 1 column to the left
 - Shift B by 1 row to the up
 - Repeat \sqrt{p} times
- All shifts wrap around (circular)









Process P(1,2) owns After initialization: A(1,2), B(1,2), C(1,2)

After skewing: A(1,0), B(0,2), C(1,2)

Shifting once: A(1,1), B(1,2), C(1,2)

Shifting twice: A(1,2), B(2,2), C(1,2)







Cannon's Algorithm – Pseudo Code

```
For i = 0 to sqrt(p) - 1
    Shift A(i,:) to the left by i

For j = 0 to sqrt(p) - 1
    Shift B(:,j) to the up by j

For k = 0 to sqrt(p) - 1
    For i = 0 to sqrt(p) - 1 and j = 0 to sqrt(p) - 1
        C(i,j) += A(i,j) X B(i,j)
        Shift A(i,:) to the left by 1
        Shift B(:,j) to the up by 1
```



